

ON STABILITY OF BLOW-UP SOLUTIONS OF THE BURGERS VORTEX TYPE FOR THE NAVIER-STOKES EQUATIONS WITH A LINEAR STRAIN

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Abstract We study the three-dimensional Navier-Stokes equations in the presence of the axisymmetric linear strain, where the strain rate depends on time in a specific manner. It is known that the system admits solutions which blow up in finite time and whose profiles are in a backward self-similar form of the familiar Burgers vortices. In this paper it is shown that the existing stability theory of the Burgers vortex leads to the stability of these blow-up solutions as well. The secondary blow-up is also observed when the strain rate is relatively weak.

Keywords Navier-Stokes equations · blow-up solutions · Burgers vortex · stability · backward self-similarity

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1. INTRODUCTION

One of the important mechanisms in three-dimensional turbulent flows is the vorticity amplification due to stretching and vorticity dissipation due to viscosity. As a simple model, the vorticity amplification induced by linear straining flows has been widely studied. A famous example is the Burgers vortex [1], which describes a vortical structure localized in a tubelike domain due to the background axisymmetric linear strain (see also [26, 12, 21, 22] for the study when the linear strain is not necessarily axisymmetric). Let us consider the three-dimensional Navier-Stokes equations for viscous incompressible flows

$$(1) \quad \partial_t V - \Delta V + \nabla P + V \cdot \nabla V = 0 \quad \nabla \cdot V = 0, \quad t > 0, \quad x \in \mathbb{R}^3.$$

The Burgers vortex [1] is the steady state solution to (1) of the form

$$(2) \quad \begin{aligned} V^{rB}(x) &= \frac{\gamma}{2} \begin{pmatrix} -x_1 \\ -x_2 \\ 2x_3 \end{pmatrix} + \frac{\alpha(1 - e^{-\frac{\gamma|x'|^2}{4}})}{2\pi|x'|^2} \begin{pmatrix} -x_2 \\ x_1 \\ 0 \end{pmatrix}, \quad x' = (x_1, x_2), \\ P^{rB}(x) &= -\frac{1}{2}|V^{rB}(x)|^2 - \frac{\alpha^2\gamma}{16\pi^2} \int_{\gamma|x'|^2}^{\infty} \frac{1}{r}(1 - e^{-\frac{r}{4}})e^{-\frac{r}{4}} dr, \end{aligned}$$

where $\gamma > 0$ and $\alpha \in \mathbb{R}$ are given constants which respectively represent the strain rate and the circulation at infinity. The corresponding vorticity field $\Omega^{rB} = \nabla \times V^{rB}$ is given by

$$(3) \quad \Omega^{rB}(x) = \begin{pmatrix} 0 \\ 0 \\ \alpha\gamma g(\gamma^{\frac{1}{2}}x') \end{pmatrix}, \quad g(X') = \frac{1}{4\pi} e^{-\frac{|X'|^2}{4}}.$$

To fix the notation, let

$$(4) \quad U^G(x') = \frac{1 - e^{-\frac{|x'|^2}{4}}}{2\pi|x'|^2} \begin{pmatrix} -x_2 \\ x_1 \\ 0 \end{pmatrix} \quad \text{and} \quad G(x') = \begin{pmatrix} 0 \\ 0 \\ g(x') \end{pmatrix}.$$

The stability of the Burgers vortex is studied in detail by now, and remarkably, it is stable for any $\gamma > 0$ and all $\alpha \in \mathbb{R}$, locally with respect to three-dimensional perturbations and globally with respect to two-dimensional perturbations. Indeed, the local two-dimensional stability for small circulation is proved by Giga-Kambe [14] and global stability for arbitrary size of circulation is proved by Gallay-Wayne [10]. The three-dimensional local stability for small circulation is shown by Gallay-Wayne [11], and the restriction on the size of circulation is removed by Gallay-Maekawa [7] also for the three-dimensional perturbations. The reader is referred to the survey of Gallay-Maekawa [8] about the existence and the stability problem related to the Burgers vortex.

Although the Burgers vortex presents in a simple way a nontrivial swirling (when $\alpha \neq 0$) flow exhibiting the balance between the vorticity stretching and dissipation, it is a nondecaying (or even growing) solution to the Navier-Stokes equations (1), and it is well known that we do not have uniqueness for such flows in general. A typical example is given by the so-called parasitic solutions. Let $\rho : [0, \infty) \rightarrow \mathbb{R}$ with $\rho(0) = \rho_0$ be a bounded differentiable function. Then

$$V(x, t) = C\rho(t), \quad P(x, t) = -\rho'(t)C \cdot x, \quad C \in \mathbb{R}^3$$

is a solution to (1) with initial data $C\rho_0$. If one considers the initial data in the form of the linear strain $\rho_0(-x_1, -x_2, 2x_3)^\top$ one finds that

$$(5) \quad V^{lin}(x, t) = \rho(t) \begin{pmatrix} -x_1 \\ -x_2 \\ 2x_3 \end{pmatrix}, \quad P(x, t) = -\frac{1}{2}|V^{lin}(x, t)|^2 - \frac{1}{2}\partial_t V^{lin}(x, t) \cdot x$$

is a solution to (1), with a pressure growing quadratically. In these examples, the function $\rho(t)$ is in principle taken arbitrary, and in particular, one may take it in a singular way so that it blows up at a finite time $T_* > 0$. In view of the linear strain V^{lin} above, it is then natural to look for a solution of the Burgers vortex type but with a time-dependent linear strain which blows up in a finite time, though the function $\rho(t)$ for the strain rate cannot be arbitrary any longer and should be chosen suitably in this case. Significant contributions in this direction have been made by Moffatt [19] and Ohkitani-Okamoto [29]. Indeed, Moffatt [19] provided a family of blowing-up solutions as follows: for $\mu > 1$ and $\alpha \in \mathbb{R}$,

(6)

$$V^{sB}(x, t) = \frac{\mu}{2(T^* - t)} \begin{pmatrix} -x_1 \\ -x_2 \\ 2x_3 \end{pmatrix} + \alpha\sqrt{\beta_\mu(t)}U^G(\sqrt{\beta_\mu(t)}x'), \quad \beta_\mu(t) = \frac{\mu - 1}{T^* - t},$$

$$P^{sB}(x, t) = -\frac{1}{2}\partial_t V^{lin}(x, t) \cdot x - \frac{1}{2}|V^{sB}(x, t)|^2 - \frac{\alpha^2\beta_\mu(t)}{16\pi^2} \int_{\beta_\mu(t)|x'|^2}^{\infty} \frac{1}{r}(1 - e^{-\frac{r}{4}})e^{-\frac{r}{4}} dr,$$

where V^{lin} is (5) with $\rho(t) = \frac{\mu}{2(T^* - t)}$ and the formula of the pressure is obtained by using the general identity $u \cdot \nabla u = \frac{1}{2}\nabla|u|^2 - u \times \omega$ with $\omega = \nabla \times u$, by also noting the fact that $U^G \times (\nabla \times U^G) = 0$ and $\nabla \times V^{lin} = 0$. Indeed, by noticing that the corresponding vorticity field is

$$(7) \quad \Omega^{sB}(x, t) = \alpha\beta_\mu(t)G(\sqrt{\beta_\mu(t)}x')$$

with G defined in (4), we have

$$\begin{aligned} & \partial_t V^{sB} + V^{sB} \cdot \nabla V^{sB} - \Delta V^{sB} \\ &= \partial_t V^{lin} + \partial_t \left(\alpha \sqrt{\beta_\mu(t)} U^G(\sqrt{\beta_\mu(t)} x') \right) + \frac{1}{2} \nabla |V^{sB}|^2 - V^{sB} \times \Omega^{sB} + \nabla \times \Omega^{sB} \\ &= \partial_t V^{lin} + \frac{1}{2} \nabla |V^{sB}|^2 - \alpha \sqrt{\beta_\mu(t)} U^G(\sqrt{\beta_\mu(t)} x') \times \Omega^{sB} \\ & \quad + \partial_t \left(\alpha \sqrt{\beta_\mu(t)} U^G(\sqrt{\beta_\mu(t)} x') \right) - V^{lin} \times \Omega^{sB} + \nabla \times \Omega^{sB}. \end{aligned}$$

Then the first three terms in the right-hand side are written as the potential form and hence define the pressure as stated above. On the other hand, we see from $\partial_t \sqrt{\beta_\mu(t)} = \frac{1}{2(\mu-1)} \beta_\mu(t)^{\frac{3}{2}}$,

$$\begin{aligned} & \partial_t \left(\alpha \sqrt{\beta_\mu(t)} U^G(\sqrt{\beta_\mu(t)} x') \right) \\ &= \frac{\alpha \beta_\mu(t)^{\frac{3}{2}}}{\mu-1} \left(\frac{1}{2} U^G(\sqrt{\beta_\mu(t)} x') + \frac{1}{2} \sqrt{\beta_\mu(t)} x' \cdot \nabla' U^G(\sqrt{\beta_\mu(t)} x') \right) \end{aligned}$$

and

$$\begin{aligned} -V^{lin} \times \Omega^{sB} + \nabla \times \Omega^{sB} &= \frac{\alpha \beta_\mu(t)^2}{2(\mu-1)} g(\sqrt{\beta_\mu(t)} x') \begin{pmatrix} x_2 \\ -x_1 \\ 0 \end{pmatrix} \\ &= \frac{\alpha \beta_\mu(t)^{\frac{3}{2}}}{\mu-1} \Delta U^G(\sqrt{\beta_\mu(t)} x'). \end{aligned}$$

Thus the conclusion holds from the identity $\Delta U^G(\xi') + \frac{1}{2} \xi' \cdot \nabla' U^G(\xi') + \frac{1}{2} U^G(\xi') = 0$.

The flow (6) blows up in a backward self-similar form and has a very similar vortical structure to the Burgers vortex. In this paper we call V^{sB} the singular Burgers vortex. Let us notice that, due to the presence of the linear strain, the singular Burgers vortex is out of the theory of Caffarelli-Kohn-Nirenberg [2] for ε -regularity for Navier-Stokes equations, and of Nečas-Ružička-Šverák [28] and Tsai [38] for the non existence of backward self-similar solutions.

What is interesting in (6) is the restriction $\mu > 1$, that is, the strain rate has to be strong enough to define the singular Burgers vortex as a *real* flow. For the specific choice of the circulation number α , Ohkitani-Okamoto [29] provided an alternative interpretation for this time-dependent strain rate in the singular Burgers vortex. Indeed, when $\alpha = \alpha_\mu = \frac{4\pi\mu}{\mu-1}$ one finds that the identity $\frac{\mu}{2(T^*-t)} = \frac{\|\nabla \times V^{sB}(\cdot, t)\|_{L^\infty}}{2}$ holds, that is, the strain rate behaves as if it depends on the unknown variable, i.e., the L^∞ norm of the vorticity field. This gives an interesting perspective in view of the Taylor expansion about x of the velocity around the origin. The analysis in this direction has been developed further by Nakamura-Okamoto-Yagisita [27] and Okamoto [30].

From now on we focus our attention on the singular Burgers vortex V^{sB} . Without loss of generality, we normalize the blow-up time as 1, i.e., $T^* = 1$. The aim of this paper is to study the asymptotic stability of the explicit blowing-up solutions (6)-(7). To simplify the notations we set

$$\begin{aligned} U_\mu(x', t) &= \sqrt{\beta_\mu(t)} U^G(\sqrt{\beta_\mu(t)} x'), \\ G_\mu(x', t) &= \beta_\mu(t) G(\sqrt{\beta_\mu(t)} x'). \end{aligned}$$

Let us go back to (1) and recall that the vorticity field $\Omega = \nabla \times V$ satisfies the equations

$$(8) \quad \partial_t \Omega - \Delta \Omega + V \cdot \nabla \Omega - \Omega \cdot \nabla V = 0, \quad \nabla \cdot \Omega = 0,$$

which are formally equivalent to (1). We note that the divergence free condition $\nabla \cdot \Omega = 0$ is preserved under the evolution equation in (8), and thus, if the initial vorticity is divergence free then the second equation in (8) is automatically satisfied. Hence we will always drop the divergence free condition for the vorticity field from now on. To study the stability of (6)-(7), we consider the solution (Ω, V) to (8) of the form $(\Omega, V) = (\Omega^{sB} + \omega, V^{sB} + u)$. Then we have from (8) the evolution equations for the perturbation vorticity ω , which reads

$$(9) \quad \partial_t \omega - \Delta \omega + \frac{\mu}{1-t} (Mx \cdot \nabla \omega - M\omega) + \alpha \mathbf{\Lambda}_\mu(t) \omega = -u \cdot \nabla \omega + \omega \cdot \nabla u$$

$$\omega|_{t=0} = \omega_0,$$

and

$$(10) \quad \mathbf{\Lambda}_\mu(t) \omega = U_\mu(t) \cdot \nabla \omega + u \cdot \nabla G_\mu(t) - \omega \cdot \nabla U_\mu(t) - G_\mu(t) \cdot \nabla u.$$

Here the matrix M is given by

$$M = \begin{pmatrix} -\frac{1}{2} & 0 & 0 \\ 0 & -\frac{1}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix},$$

and the perturbation velocity u is formally recovered from the vorticity ω by the Biot-Savart law

$$(11) \quad u(x, t) = -\frac{1}{4\pi} \int_{\mathbb{R}^3} \frac{(x-y) \times \omega(y, t)}{|x-y|^3} dy = (K_{3D} * \omega(t))(x),$$

by assuming a suitable spatial decay on ω . The goal of this paper is to study the behavior of ω up to $T^* = 1$ for a suitable class of the initial data ω_0 . In particular, to show the asymptotic stability of the blowing-up solution (Ω^{sB}, V^{sB}) , we aim at establishing $(1-t)^{\frac{1}{2}} \|u(t)\|_{L^\infty} \rightarrow 0$ as $t \uparrow 1$.

As in the work of Lundgren [18] for the strained Navier-Stokes equations and of Giga-Kohn [15] for the nonlinear heat equation, it is convenient to introduce the self-similar variables:

$$\tau = -(\mu - 1) \log(1 - t), \quad \xi = \sqrt{\beta_\mu(t)} x, \quad \beta_\mu(t) = \frac{\mu - 1}{1 - t},$$

and

$$(12) \quad u(x, t) = \sqrt{\beta_\mu(t)} \mathcal{V}(\xi, \tau), \quad \omega(x, t) = \beta_\mu(t) \mathcal{W}(\xi, \tau).$$

Then the system for \mathcal{W} is written as

$$(13) \quad \partial_\tau \mathcal{W} - (L_\mu - \alpha \mathbf{\Lambda}) \mathcal{W} = -\mathcal{V} \cdot \nabla \mathcal{W} + \mathcal{W} \cdot \nabla \mathcal{V} \quad \tau > 0, \quad \xi \in \mathbb{R}^3,$$

$$\mathcal{W}|_{\tau=0} = \mathcal{W}_0,$$

where

$$(14) \quad L_\mu \mathcal{W} = \Delta \mathcal{W} + \frac{\xi'}{2} \cdot \nabla' \mathcal{W} - \frac{2\mu + 1}{2(\mu - 1)} \xi_3 \partial_3 \mathcal{W} + \frac{1}{\mu - 1} (\mu M - I) \mathcal{W}$$

and

$$(15) \quad \mathbf{\Lambda} \mathcal{W} = U^G \cdot \nabla \mathcal{W} + \mathcal{V} \cdot \nabla G - \mathcal{W} \cdot \nabla U^G - G \cdot \nabla \mathcal{V}.$$

Here $\mathcal{V} = K_{3D} * \mathcal{W}$, and U^G and G are defined in (4). Hence, by using the self-similar variables (ξ, τ) the study of the behavior of ω around the blow-up time $T^* = 1$ is translated into the large time behavior of \mathcal{W} , and the problem shares common features in essence with

the stability problem of the Burgers vortex for which a detailed analysis was done. Indeed, if we set the differential operator L as

$$(16) \quad Lw = \Delta w + \frac{\xi'}{2} \cdot \nabla' w - \xi_3 \partial_3 w + Mw,$$

which is formally obtained by taking the limit $\mu \rightarrow \infty$ in (14), then the linear operator $L - \alpha\Lambda$ is exactly the linearized operator around the Burgers vortex with circulation α . It is studied in [7] for all circulation number $\alpha \in \mathbb{R}$, and the uniform spectral gap of $-\frac{1}{2}$ is achieved for all α in a suitable functional setting. Since the only difference between L_μ and L is the stretching term related to $\xi_3 \partial_3$, it is natural to expect that the operator $L_\mu - \alpha\Lambda$ also has a uniform spectral gap under the similar functional framework as in [7]. This implies that the original blowing-up solution (6)-(7) is asymptotically stable under the small perturbations as long as $\mu > 1$. Our main theorem is the following stability result stated in Theorem 1 below, which is in the spirit of stability results for blowing-up solutions of the nonlinear heat equation [25] or of dispersive equations [24]. As far as the authors know, this is the first result of this type for the Navier-Stokes equations, though the key stability mechanism is brought by the singular linear strain and hence the spatial growth of the solution plays an important role. The function spaces used in the theorem are defined in the paragraph **Notations** below. It is shown that $L_\mu - \alpha\Lambda$ generates a semigroup $e^{\tau(L_\mu - \alpha\Lambda)}$ in the function space $\mathbb{X}(m)$ defined in **Notations** and then the mild solution \mathcal{W} to (13) (with the initial data \mathcal{W}_0) is defined as the solution to the integral equation

$$\begin{aligned} \mathcal{W}(\tau) &= e^{\tau(L_\mu - \alpha\Lambda)} \mathcal{W}_0 + \int_0^\tau e^{(\tau-s)(L_\mu - \alpha\Lambda)} \left(-\mathcal{V} \cdot \nabla \mathcal{W} + \mathcal{W} \cdot \nabla \mathcal{V} \right) ds, \\ \mathcal{V} &= K_{3D} * \mathcal{W}. \end{aligned}$$

Then we call ω the mild solution to (9) when ω is given by the transformation (12) for \mathcal{W} .

Theorem 1 (stability of the singular Burgers vortex). *Let $\alpha \in \mathbb{R}$, $m \in (2, \infty]$, $\mu \in (1, \infty)$. Let $\omega_{0,2d} \in L_0^2(m)$. Then there exists $\varepsilon = \varepsilon(\alpha, m, \mu, \omega_{0,2d}) \in (0, 1)$ such that the following statement holds. For all divergence-free $\omega_0 \in \mathbb{X}(m)$ satisfying*

$$\omega_0 = (0, 0, \omega_{0,2d}(x')) + \omega_{0,3d}(x', x_3), \quad \|\omega_{0,3d}\|_{\mathbb{X}(m)} \leq \varepsilon,$$

there exists a unique mild solution $\omega \in L_{loc}^\infty([0, 1); \mathbb{X}(m))$ to (9) such that $t^{\frac{1}{2}} \partial_x^\beta \omega \in L_{loc}^\infty([0, 1); \mathbb{X}(m))$ with $|\beta| \leq 1$. This solution satisfies

$$\limsup_{t \rightarrow 1} (1-t)^{\frac{1}{2} - \frac{\mu-1}{2}} \|u(\cdot, t)\|_{L^\infty(\mathbb{R}^3)} < \infty,$$

*where $u = K_{3d} * \omega$. Moreover, if $\alpha \neq 0$, letting*

$$\lambda_i = -\sqrt{\mu-1} \int_{\mathbb{R}^2} x_i \omega_{0,2d}(x') dx', \quad i = \{1, 2\},$$

we have the following asymptotic estimate for u :

$$(17) \quad \limsup_{t \rightarrow 1} (1-t)^{\frac{1}{2} - \frac{\mu-1}{2}} \left\| u(\cdot, t) - (1-t)^{\frac{\mu-1}{2}} \sum_{i=1,2} \lambda_i \sqrt{\frac{\mu-1}{1-t}} (\partial_i U^G) \left(\sqrt{\frac{\mu-1}{1-t}} \cdot \right) \right\|_{L^\infty(\mathbb{R}^3)} \leq C\varepsilon.$$

Here C depends on α, m, μ , and $\omega_{0,2d}$.

Remark 1. (1) Let us notice that $V = V^{sB} + u$ is a solution to the Navier-Stokes system (1). A way to rephrase the asymptotic expansion (17) is as follows:

$$\begin{aligned} V(x, t) &= V^{sB}(x, t) + \sqrt{\mu - 1}(1 - t)^{\frac{\mu}{2} - 1} \sum_{i=1,2} \lambda_i (\partial_i U^G) \left(\sqrt{\frac{\mu - 1}{1 - t}} x \right) \\ &\quad + O_{L^\infty}(\epsilon(1 - t)^{\frac{\mu}{2} - 1}) + o_{L^\infty}((1 - t)^{\frac{\mu}{2} - 1}). \end{aligned}$$

Hence in the vicinity of V^{sB} , we have constructed a whole family of blowing-up solutions. Moreover, when $\alpha, \lambda_i \neq 0$, if the strain is sufficiently weak so that $\mu \in (1, 2)$, then we identify a leading part (in ϵ) of the secondary blow-up profile in the sense that the term $\sqrt{\mu - 1}(1 - t)^{\frac{\mu}{2} - 1} \sum_{i=1,2} \lambda_i (\partial_i U^G) \left(\sqrt{\frac{\mu - 1}{1 - t}} x \right)$ blows up as well in the L^∞ norm. In fact, as seen in the proof (and the last statement of Theorem 2 and its remark below) the secondary blow up profile is still a linear combination of $\sqrt{\mu - 1}(1 - t)^{\frac{\mu}{2} - 1} (\partial_i U^G) \left(\sqrt{\frac{\mu - 1}{1 - t}} x \right)$ but in a weaker topology. Precisely, we can show that there exist $d_i \in \mathbb{R}$, $i = 1, 2$, such that

$$\begin{aligned} (18) \quad &\lim_{t \rightarrow 1} (1 - t)^{\frac{1}{2} - \frac{\mu - 1}{2}} \|u(\cdot, t) \\ &\quad - (1 - t)^{\frac{\mu - 1}{2}} \sum_{i=1,2} (\lambda_i + d_i) \sqrt{\frac{\mu - 1}{1 - t}} (\partial_i U^G) \left(\sqrt{\frac{\mu - 1}{1 - t}} \cdot \right) \|_{L_{x_3}^\infty([-N, N]; L_{x'}^\infty)} = 0, \end{aligned}$$

for any $N > 0$. Here d_i satisfies $|d_i| \leq C \|\omega_{0,3d}\|_{\mathbb{X}(m)} \ll 1$ with C depending only on α , m , μ , and $\omega_{0,2d}$.

(2) In Theorem 1 the initial data $\omega_{0,2d} \in L_0^2(m)$ is taken arbitrary, while we do not have a quantitative information between $\|\omega_{0,2d}\|_{L^2(m)}$ and the small constant ϵ for the three-dimensional perturbation. On the other hand, for small initial data in $\mathbb{X}(m)$ the condition in Theorem 1 can be stated in a more quantitative way as follows; there exists $\epsilon = \epsilon(\alpha, m, \mu) > 0$ such that, if the (divergence-free) initial data $\omega_0 \in \mathbb{X}(m)$ satisfies $\|\omega_0\|_{\mathbb{X}(m)} \leq \epsilon$, then the stability estimate such as (17) or (18) for the solution is verified with a constant C depending only on α , m , and μ (here C is taken independently of ω_0 , since $\|\omega_0\|_{\mathbb{X}(m)} \leq \epsilon$ and ϵ is small enough).

(3) It should be emphasized that the uniqueness of the solution in Theorem 1 is claimed for the equation (9), and not for the original Navier-Stokes equation (1). Indeed, as already explained, we do not have the uniqueness of solutions to (1) for nondecaying initial data. Roughly speaking, the uniqueness holds for the class of solutions having the form $V = V^{sB} + u$ with decaying (in the horizontal direction) u .

Outline of the paper. In Section 2 we handle the stability analysis of the linear equation

$$\partial_\tau w - (L_\mu - \alpha \mathbf{\Lambda})w = 0.$$

The goal of the analysis is to extend the arguments of Gallay-Maekawa [7] to the case of the operator $L_\mu - \alpha \mathbf{\Lambda}$. Section 3 is devoted to the proof of nonlinear stability. More precisely, we prove that the zero solution of the nonlinear equation (13) is stable under arbitrarily large two-dimensional perturbations, and small genuinely three-dimensional perturbations, see Theorem 2. Such a result is in the spirit of [31], though the technique we use is different. Instead of continuing the solution via a blow-up criteria as in [31], we construct a mild solution iteratively until the source becomes small enough for global in time solutions to exist. We conclude this by investigating the existence of a secondary blow-up profile. Theorem 1 immediately follows from the results of Section 3 by scaling back to the original variables (x, t) .

Notations. As is usual, we always decompose $x = (x', x_3) \in \mathbb{R}^3$ or $\xi = (\xi', \xi_3) \in \mathbb{R}^3$ into horizontal component $x' = (x_1, x_2) \in \mathbb{R}^2$ or $\xi' = (\xi_1, \xi_2) \in \mathbb{R}^2$, and vertical component x_3 or ξ_3 . Similarly, we write $\nabla' = (\partial_{x_1}, \partial_{x_2})$ and $\Delta' = \partial_{x_1}^2 + \partial_{x_2}^2$. Throughout the paper, we work in the following functional setting. For $m \in [0, \infty]$ set

$$\rho_m(r) = \begin{cases} 1, & m = 0, \\ (1 + \frac{r}{4m})^m, & 0 < m < \infty, \\ e^{\frac{r}{4}}, & m = \infty. \end{cases}$$

For $p \in [1, \infty)$, we define the weighted spaces

$$L^p(m) = \left\{ w \in L^p(\mathbb{R}^2) \mid \|w\|_{L^p(m)}^2 = \int_{\mathbb{R}^2} |w(x')|^p \rho_m(|x'|^2)^{\frac{2}{p}} dx' \right\},$$

$$L_0^p(m) = \left\{ w \in L^p(m) \mid \int_{\mathbb{R}^2} w dx' = 0 \right\} \quad \text{for } m > 2 - \frac{2}{p}.$$

Moreover, we use the following product spaces: for $p \in [1, \infty)$ and $m > 2 - \frac{2}{p}$

$$X^p(m) = BC(\mathbb{R}; L^p(m)), \quad X_0^p(m) = BC(\mathbb{R}; L_0^p(m)),$$

with $\|\phi\|_{X^p(m)} = \sup_{x_3 \in \mathbb{R}} \|\phi(\cdot, x_3)\|_{L^p(m)}$,

$$\mathbb{X}^p(m) = X^p(m) \times X^p(m) \times X_0^p(m),$$

where “ $BC(\mathbb{R}; Y)$ ” denotes the space of all bounded and continuous functions from \mathbb{R} to a Banach space Y . We denote by $X_{loc}^p(m)$ the subspace of $X^p(m)$ endowed with the topology given by the seminorms $(\|\cdot\|_{X_n^p(m)})_{n \in \mathbb{N}}$ defined by

$$\|\phi\|_{X_n^p(m)} = \sup_{|x_3| \leq n} \|\phi(\cdot, x_3)\|_{L^p(m)}, \quad \forall \phi \in X^p(m), \quad n \in \mathbb{N}.$$

We then set in analogy with above $\mathbb{X}_{loc}^p(m) = X_{loc}^p(m) \times X_{loc}^p(m) \times X_{loc,0}^p(m)$, where $X_{loc,0}^p(m)$ is $X_0^p(m)$ equipped with the topology of $X_{loc}^p(m)$. When $p = 2$ and $m > 1$, we use the abbreviations $X(m)$, $X_0(m)$ and $\mathbb{X}(m)$ and analogously for the “loc” versions. These spaces are used in [7].

2. ANALYSIS OF THE LINEARIZED OPERATOR

This section is centered on the analysis of the semigroup $e^{\tau(L_\mu - \alpha\Lambda)}$ for the linear evolution. The main result is the following.

Proposition 2 (linear stability). *Let $\alpha \in \mathbb{R}$, $m \in (1, \infty]$, $\mu \in (1, \infty)$ and $p \in [1, 2]$. Then for all $\eta \in (0, \frac{1}{2}]$ with $\eta < \frac{m-1}{2}$, $\kappa \in (0, \eta + \frac{2\mu+1}{2(\mu-1)})$, and $\beta \in \mathbb{N}^3$, there exists a constant $C(\alpha, m, \mu, \kappa, \eta, \beta) < \infty$ such that*

$$(19) \quad \|\partial_\xi^\beta (e^{\tau(L_\mu - \alpha\Lambda)} w_0)'\|_{X(m)^2} \leq \frac{C e^{-(\kappa + \frac{2\mu+1}{2(\mu-1)})\beta_3 \tau}}{a(\tau)^{\frac{1}{p} - \frac{1}{2} + \frac{|\beta|}{2}}} \|w_0\|_{\mathbb{X}^p(m)}$$

$$(20) \quad \|\partial_\xi^\beta (e^{\tau(L_\mu - \alpha\Lambda)} w_0)_3\|_{X(m)} \leq \frac{C e^{-(\eta + \frac{2\mu+1}{2(\mu-1)})\beta_3 \tau}}{a(\tau)^{\frac{1}{p} - \frac{1}{2} + \frac{|\beta|}{2}}} \|w_0\|_{\mathbb{X}^p(m)}$$

for all divergence-free $w_0 \in \mathbb{X}^p(m)$ and $\tau \in (0, \infty)$, where $a(\tau) = 1 - e^{-\tau}$. Moreover,

$$\int_{\mathbb{R}^2} (e^{\tau(L_\mu - \alpha\Lambda)} w_0)_3(\xi', \xi_3) d\xi' = 0,$$

and $\nabla \cdot w_0 = 0$ implies $\nabla \cdot e^{\tau(L_\mu - \alpha\Lambda)} w_0 = 0$ for all $\tau \in (0, \infty)$. If $\eta < \frac{1}{2}$ then κ is taken as $\kappa = \eta + \frac{2\mu+1}{2(\mu-1)}$.

Corresponding estimates for the Burgers vortex are obtained and used in [7]. The gain in the decay for ξ_3 derivatives in (19) and (20) is due to the commutation property stated in (40) below, which is already used in [3, 35, 36, 7]. This property is an effect of the stretching in the vertical direction due to the structure of the linear strain, which is a key stabilizing effect of the Burgers vortex. Another remark concerns the transient growth. There is a factor $a(\tau)^{-\left(\frac{1}{p}-\frac{1}{2}+\frac{|\beta|}{2}\right)}$ related to the parabolic-type smoothing effect of $e^{\tau(L_\mu-\alpha\Lambda)}$, which is large in short time. This factor does not depend on α . The constant C in (19) and (20), though, gets large when $\alpha \rightarrow \infty$, $\mu \rightarrow 1^+$. We note that the estimate of $e^{\tau(L_\mu-\alpha\Lambda)}$ for local time is not difficult to show:

$$(21) \quad \|\partial_\xi^\beta e^{\tau(L_\mu-\alpha\Lambda)} w_0\|_{\mathbb{X}(m)} \leq \frac{C}{a(\tau)^{\frac{1}{p}-\frac{1}{2}+\frac{|\beta|}{2}}} \|w_0\|_{\mathbb{X}^p(m)}, \quad 0 < \tau \leq 1, \quad p \in [1, 2].$$

Here C depends only on α , μ and m ; see, e.g., the argument of [7, Proposition 4.2]. Thus, by recalling the semigroup property, we may focus on the estimates (19)-(20) but only for $\tau \geq 1$ and $p = 2$.

The argument to achieve the linear stability is rather parallel to the one of Gallay-Maekawa in [7]. The idea is to decompose the full operator $L_\mu - \alpha\Lambda$ into a dominant two-dimensional (but vectorial) part and a three-dimensional part whose contribution to the solution decays fast and is negligible in the longtime. Hence we first focus on the operator L_μ . Second, we address the vectorial 2d problem, i.e. on the action of $L_\mu - \alpha\Lambda$ on fields $w = w(x')$ independent of x_3 . Finally, we analyze the full operator $L_\mu - \alpha\Lambda$ using the stretching in the vertical direction which makes the three-dimensional part of the solution decay fast.

2.1. Analysis of L_μ . Let us start from the analysis of L_μ . We first rewrite the operator similarly to [7] so as to make the comparison easier. We first expand (14) as

$$L_\mu = \Delta' + \frac{\xi'}{2} \cdot \nabla' + \partial_3^2 - \frac{2\mu+1}{2(\mu-1)} \xi_3 \partial_3 + \begin{pmatrix} -\frac{\mu+2}{2(\mu-1)} & 0 & 0 \\ 0 & -\frac{\mu+2}{2(\mu-1)} & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

Hence, we can write the action of L_μ in the following form

$$(22) \quad L_\mu w = \begin{pmatrix} L_{\mu,h} w' \\ L_{\mu,3} w_3 \end{pmatrix} = \begin{pmatrix} \mathcal{L}_h w' + \mathcal{L}_3 w' - \left(1 + \frac{\mu+2}{2(\mu-1)}\right) w' \\ \mathcal{L}_h w_3 + \mathcal{L}_3 w_3 \end{pmatrix},$$

where

$$\begin{aligned} \mathcal{L}_h &= \Delta' + \frac{\xi'}{2} \cdot \nabla' + 1, \\ \mathcal{L}_3 &= \partial_3^2 - \frac{2\mu+1}{2(\mu-1)} \xi_3 \partial_3. \end{aligned}$$

According to [11, Appendix A], the operator \mathcal{L}_h is the generator of a strongly continuous semigroup in $L^2(m)$ given by the explicit formula

$$(23) \quad (e^{\tau \mathcal{L}_h} f)(\xi') = \frac{e^\tau}{4\pi a(\tau)} \int_{\mathbb{R}^2} e^{-\frac{|\xi' - \eta'|^2}{4a(\tau)}} f(\eta' e^{\frac{\tau}{2}}) d\eta', \quad a(\tau) = 1 - e^{-\tau},$$

for all $\tau \in (0, \infty)$. Moreover, it is well known that $-\mathcal{L}_h$ is self-adjoint in $L^2(\infty)$ and satisfies the following lower bounds (cf. [10, Lemma 4.7]):

$$(24) \quad -\mathcal{L}_h \geq 0 \quad \text{in } L^2(\infty), \quad -\mathcal{L}_h \geq \frac{1}{2} \quad \text{in } L_0^2(\infty), \quad -\mathcal{L}_h \geq 1 \quad \text{in } L_1^2(\infty),$$

where $L_1^2(\infty) = \{f \in L_0^2(\infty) \mid \int_{\mathbb{R}^2} \xi_j f d\xi = 0, j = 1, 2\}$. As for \mathcal{L}_3 , it is the generator of a semigroup of contractions in $BC(\mathbb{R})$ with the following explicit formula, which is derived

from [11, Appendix A]) for the semigroup generated by the differential operator of the form $\partial_3^2 - b\xi_3\partial_3 - b$.

$$(25) \quad (e^{\tau\mathcal{L}_3}f)(\xi_3) = \left(\frac{2\chi}{4\pi(e^{2\chi\tau}-1)}\right)^{\frac{1}{2}} \int_{\mathbb{R}} \exp\left(-\frac{2\chi|\xi_3-\eta_3|^2}{4(e^{2\chi\tau}-1)}\right) f(\eta_3 e^{-\chi\tau}) d\eta_3,$$

for all $\tau \in (0, \infty)$, where

$$(26) \quad \chi = \chi_\mu = \frac{2\mu+1}{2(\mu-1)}.$$

Notice that $\chi > 1$. We can rewrite formula (25):

$$(27) \quad (e^{\tau\mathcal{L}_3}f)(\xi_3) = \left(\frac{\chi}{2\pi a(2\chi\tau)}\right)^{\frac{1}{2}} \int_{\mathbb{R}} e^{-\frac{\chi|e^{-\chi\tau}\xi_3-\eta_3|^2}{2a(2\chi\tau)}} f(\eta_3) d\eta_3, \quad a(\tau) = 1 - e^{-\tau},$$

for all $\tau \in (0, \infty)$. From the previous formula, we immediately obtain the fast temporal decay of derivatives of $e^{\tau\mathcal{L}_3}f$. Indeed, for all $k \in \mathbb{N}$, there exists a constant $C(k) < \infty$ such that for all $\tau \in (0, \infty)$,

$$(28) \quad \left\| \partial_3^k e^{\tau\mathcal{L}_3}f \right\|_{L^\infty(\mathbb{R})} \leq C \frac{\chi^{\frac{k}{2}} e^{-\chi k\tau}}{a(2\chi\tau)^{\frac{k}{2}}} \|f\|_{L^\infty(\mathbb{R})},$$

where χ is defined in (26). Moreover, we also have from (27),

$$(29) \quad \lim_{\tau \rightarrow \infty} \left\| e^{\tau\mathcal{L}_3}f - \left(\frac{\chi}{2\pi}\right)^{\frac{1}{2}} \int_{\mathbb{R}} e^{-\frac{\chi|\eta_3|^2}{2}} f(\eta_3) d\eta_3 \right\|_{L^\infty([-e^{(\chi-\delta)\tau}, e^{(\chi-\delta)\tau}])} = 0,$$

for any $\delta > 0$.

The fast decay (28), due to the strong stretching in the vertical direction, plays a key role in the fact that the linear evolution becomes independent of x_3 at the main order. Hence, the leading dynamics in the longtime is driven by the 2d vectorial problem, which we analyze in the next subsection.

2.2. Localization in the horizontal direction: the 2d vectorial problem. In this subsection we analyze the 2d vectorial problem, which corresponds with the action of $e^{\tau(L_\mu - \alpha\Lambda)}$ on the functions of the form $w = w(\xi') \in \mathbb{R}^3$, i.e., $\partial_3 w = 0$. We define for $\alpha \in \mathbb{R}$ and $\mu \in (1, \infty)$,

$$(30) \quad \mathcal{L}_{\mu,\alpha}w = \begin{pmatrix} \mathcal{L}_{\mu,\alpha,h}w' \\ \mathcal{L}_{\mu,\alpha,3}w_3 \end{pmatrix} = \begin{pmatrix} (\mathcal{L}_h - 1 - \frac{\mu+2}{2(\mu-1)})w' - \alpha(\Lambda_1 - \tilde{\Lambda}_2)w' \\ \mathcal{L}_h w_3 - \alpha(\Lambda_1 + \tilde{\Lambda}_3)w_3 \end{pmatrix}.$$

Here

$$\Lambda_1 w = U^G \cdot \nabla w = (U^G)' \cdot \nabla' w,$$

$$\tilde{\Lambda}_2 w' = w' \cdot \nabla'(U^G)',$$

$$\tilde{\Lambda}_3 w_3 = (K_{2d} * w_3) \cdot \nabla' g.$$

The operators Λ_1 and $\tilde{\Lambda}_3$ come from the vorticity transport, while $\tilde{\Lambda}_2$ originates from the vortex stretching term. One can check that $L_\mu - \alpha\Lambda w = \mathcal{L}_{\mu,\alpha}w$ when $\partial_3 w = 0$; see identity (42) and inequality (43). Notice that the horizontal w' and the vertical components w_3 are completely decoupled. This makes the 2d vectorial problem more tractable than the full original one. The operator $\mathcal{L}_{\mu,\alpha,3}$ and the associated semigroup in $L_0^2(m)$ are already analyzed in [10, Section 4]. The main result of this section is stated as follows.

Proposition 3 (2d vectorial problem). *Let $\alpha \in \mathbb{R}$, $m \in (1, \infty]$, $\mu \in (1, \infty)$. Then for all $\kappa \in (0, 1 + \frac{\mu+2}{2(\mu-1)})$, for all $\eta \in (0, \frac{1}{2}]$ such that $\eta < \frac{m-1}{2}$, there exists a constant $C(\alpha, m, \mu, \kappa, \eta) < \infty$ such that*

$$\begin{aligned} \|e^{\tau \mathcal{L}_{\mu, \alpha, h}} w_{0, h}\|_{L^2(m)^2} &\leq C e^{-\kappa \tau} \|w_{0, h}\|_{L^2(m)^2}, \\ \|e^{\tau \mathcal{L}_{\mu, \alpha, 3}} w_{0, 3}\|_{L^2(m)} &\leq C e^{-\eta \tau} \|w_{0, 3}\|_{L^2(m)}, \end{aligned}$$

for all $\tau \in [0, \infty)$ and for all $w_0 \in L^2(m)^2 \times L_0^2(m)$. Moreover, if $m > 2$ then for $\eta \in (\frac{1}{2}, 1]$ with $\eta < \frac{m-1}{2}$,

$$(31) \quad \left\| e^{\tau \mathcal{L}_{\mu, \alpha, 3}} w_{0, 3} - e^{-\frac{\tau}{2}} \sum_{i=1,2} \theta_i \partial_i g \right\|_{L^2(m)} \leq C e^{-\eta \tau} \|w_{0, 3}\|_{L^2(m)}.$$

Here $\theta_i = -\int_{\mathbb{R}^2} \xi_i w_{0, 3}(\xi') d\xi'$ and $g(\xi') = \frac{1}{4\pi} e^{-\frac{|\xi'|^2}{4}}$.

Note that the result for $e^{\tau \mathcal{L}_{\mu, \alpha, 3}} w_{0, 3}$ in Proposition 3 is due to [10, Section 4], in particular [10, Proposition 4.12]. The key observation there is that for suitably large m the spectrum of $\mathcal{L}_{\mu, \alpha, 3}$ in $L^2(m)$ near the imaginary axis consists of the isolated eigenvalues whose eigenfunctions actually belong to $L^2(\infty)$, and thus, the analysis of the large time behavior of $e^{\tau \mathcal{L}_{\mu, \alpha, 3}}$ in $L^2(m)$ is essentially reduced to the analysis in $L^2(\infty)$, in which \mathcal{L}_h is self-adjoint and moreover $\mathbf{\Lambda}_1 + \tilde{\mathbf{\Lambda}}_3$ is skew-symmetric; see [10, Lemma 4.8]. Then, the lower bounds in (24) enable us to conclude the expansion (31) in $L_0^2(m)$ for large enough m , by also using the fact that the eigenspace of the eigenvalue $-\frac{1}{2}$ of $\mathcal{L}_{\mu, \alpha, 3}$ in $L^2(\infty)$ is spanned by $\partial_i g$, $i = 1, 2$. On the other hand, the estimate of $e^{\tau \mathcal{L}_{\mu, \alpha, h}}$ is obtained in the same manner as in [7, Proposition 3.1], as sketched below for reader's convenience. The following lemma is the key for the study of $e^{\tau \mathcal{L}_{\mu, \alpha, h}}$. Let $r_{\text{ess}}(A; X)$ be the radius of the essential spectrum of a bounded linear operator A on X ; see [4, IV-1.20].

Lemma 4. *Let $m \in (1, \infty]$. Then the following statements hold.*

- (i) $r_{\text{ess}}(e^{\tau \mathcal{L}_{\mu, \alpha, h}}; L^2(m)) = \begin{cases} e^{-(\frac{1}{2} + \frac{\mu+2}{2(\mu-1)} + \frac{m}{2})\tau}, & m \neq \infty \\ 0, & m = \infty \end{cases}$.
- (ii) *If $\lambda \in \mathbb{C}$ with $\text{Re} \lambda \geq -\frac{1}{2} - \frac{\mu+2}{2(\mu-1)} - \frac{m}{2}$ is an eigenvalue of $\mathcal{L}_{\mu, \alpha, h}$ in $L^2(m)^2$ then $\text{Re} \lambda \leq -1 - \frac{\mu+2}{2(\mu-1)}$.*

The proof of Lemma 4 (i) is identical to the proof of [7, Proposition 3.3]. Indeed, we see that the operator $\Delta_\alpha(\tau) = e^{\tau \mathcal{L}_{\mu, \alpha, h}} - e^{\tau(\mathcal{L}_h - 1 - \frac{\mu+2}{2(\mu-1)})}$ is compact in $L^2(m)^2$ for any $m \in (1, \infty]$. Hence, Weyl's theorem implies that both semigroups have the same essential spectrum and hence have same essential radii: for all $m \in (1, \infty]$, we have $r_{\text{ess}}(e^{\tau \mathcal{L}_{\mu, \alpha, h}}; L^2(m))^2 = r_{\text{ess}}(e^{\tau(\mathcal{L}_h - 1 - \frac{\mu+2}{2(\mu-1)})}; L^2(m)^2)$. Then the fact

$$r_{\text{ess}}(e^{\tau(\mathcal{L}_h - 1 - \frac{\mu+2}{2(\mu-1)})}; L^2(m)) = \begin{cases} e^{-(\frac{1}{2} + \frac{\mu+2}{2(\mu-1)} + \frac{m}{2})\tau}, & m \neq \infty \\ 0, & m = \infty \end{cases},$$

which was proved in [11, Appendix A], yields the statement (i) of Lemma 4. Next, the proof of Lemma 4 (ii) is sketched below. By a standard argument [7, Proposition 3.4 and Section 6.2], every eigenfunction in $L^2(m)^2$ associated to an eigenvalue λ with $\text{Re}(\lambda) > -\frac{1}{2} - \frac{\mu+2}{2(\mu-1)} - \frac{m}{2}$ belongs to $L^2(\infty)^2$, i.e. has Gaussian decay. It is therefore enough to study the discrete spectrum of $\mathcal{L}_{\mu, \alpha, h}$ in $L^2(\infty)^2$, for which the same argument as in [7, Proposition 3.5] is applied as follows. The eigenfunction $w' \in L^2(\infty)^2$ associated to the

eigenvalue λ satisfies, by its definition,

$$(32) \quad \lambda w' = \mathcal{L}_h w' - \left(1 + \frac{\mu + 2}{2(\mu - 1)}\right) w' - \alpha(U^G)' \cdot \nabla' w' + \alpha w' \cdot \nabla'(U^G)'.$$

By the direct computation we also have the equations that are respectively satisfied by $\xi' \cdot w'$ and $\nabla' \cdot w'$:

$$(33) \quad \lambda \xi' \cdot w' = \mathcal{L}_h(\xi' \cdot w') - 2\nabla' \cdot w' - \frac{1}{2}\xi' \cdot w' - \left(1 + \frac{\mu + 2}{2(\mu - 1)}\right) \xi' \cdot w' - \alpha U^G \cdot \nabla'(\xi' \cdot w'),$$

$$(34) \quad \lambda \nabla' \cdot w' = \mathcal{L}_h(\nabla' \cdot w') + \frac{1}{2}\nabla' \cdot w' - \left(1 + \frac{\mu + 2}{2(\mu - 1)}\right) \nabla' \cdot w' - \alpha U^G \cdot \nabla'(\nabla' \cdot w').$$

The upper bound of $\operatorname{Re}\lambda$ is obtained from these identities (32), (33), and (34). Indeed, testing the equation (32) against $\overline{w'}$ (complex conjugate of w'), we obtain

$$(35) \quad \operatorname{Re}\lambda \|w'\|^2 = \langle \mathcal{L}_h w', w' \rangle - \left(1 + \frac{\mu + 2}{2(\mu - 1)}\right) \|w'\|^2 + 2\alpha \operatorname{Re} \left(\int_{\mathbb{R}^2} e^{\frac{|\xi'|^2}{4}} (\xi' \cdot w') (\xi'^{\perp} \cdot \overline{w'}) \partial_r(w^g) (|\xi'|^2) d\xi' \right),$$

where we used the skew-symmetry of $w' \mapsto U^G \cdot \nabla' w'$ in $L^2(\infty)^2$ equipped with the scalar product $\langle \cdot, \cdot \rangle$ defined by

$$\langle w^1, w^2 \rangle = \int_{\mathbb{R}^2} e^{\frac{|\xi'|^2}{4}} w^1 \overline{w^2} d\xi'.$$

Similarly, we have from (33) and (34),

$$(36) \quad \operatorname{Re}\lambda \|\xi' \cdot w'\|^2 = \langle \mathcal{L}_h(\xi' \cdot w'), \xi' \cdot w' \rangle - \left(\frac{3}{2} + \frac{\mu + 2}{2(\mu - 1)}\right) \|\xi' \cdot w'\|^2 - 2\operatorname{Re}\langle \nabla' \cdot w', \xi' \cdot w' \rangle,$$

and

$$(37) \quad \operatorname{Re}\lambda \|\nabla' \cdot w'\|^2 = \langle \mathcal{L}_h(\nabla' \cdot w'), \nabla' \cdot w' \rangle - \left(\frac{1}{2} + \frac{\mu + 2}{2(\mu - 1)}\right) \|\nabla' \cdot w'\|^2.$$

Now suppose that $\nabla' \cdot w'$ is not identically zero. Then (37) and (24) with the fact $\nabla' \cdot w' \in L_0^2(\infty)$ (i.e., $-\mathcal{L}_h \geq \frac{1}{2}$ in $L_0^2(\infty)$) imply $\operatorname{Re}\lambda \leq -1 - \frac{\mu+2}{2(\mu-1)}$. Next suppose that $\nabla' \cdot w'$ is identically zero but that $\xi' \cdot w'$ is not identically zero. In this case (36) and (24) (i.e., $-\mathcal{L}_h \geq 0$ in $L^2(\infty)$) imply $\operatorname{Re}\lambda \leq -\frac{3}{2} - \frac{\mu+2}{2(\mu-1)}$. Finally, suppose that $\xi' \cdot w'$ is identically zero. Then (35) and (24) give the bound $\operatorname{Re}\lambda \leq -1 - \frac{\mu+2}{2(\mu-1)}$. Therefore, we conclude

$$(38) \quad \operatorname{Re}\lambda \leq -1 - \frac{\mu + 2}{2(\mu - 1)}.$$

The statement of Lemma 4 (ii) is proved.

The estimate of $e^{\tau \mathcal{L}_{\mu, \alpha, h}}$ stated in Proposition 3 follows from Lemma 4 and the standard theory of C_0 -semigroup [4, Corollary IV-2.11], and we conclude that the growth bound of $e^{\tau \mathcal{L}_{\mu, \alpha, h}}$ in $L^2(m)^2$, $m \in (1, \infty]$, is estimated from above by $-1 - \frac{\mu+2}{2(\mu-1)}$. Thus, for any $\kappa \in (0, 1 + \frac{\mu+2}{2(\mu-1)})$ we have $\|e^{\tau \mathcal{L}_{\mu, \alpha, h}} w_{0,h}\|_{L^2(m)^2} \leq C e^{-\kappa \tau} \|w_{0,h}\|_{L^2(m)^2}$, which proves Proposition 3.

We stress that, in Proposition 3, w is a function of the horizontal variable $\xi' \in \mathbb{R}^2$ only. Notice that we do not yet have the restriction κ appearing in Proposition 2. This additional restriction comes from the analysis of the full three-dimensional problem.

2.3. The regularizing effect of vertical stretching: full 3d linear stability problem. In this subsection we complete the proof of Proposition 2. As is mentioned in the beginning of Section 2, we may focus on the case $\tau \geq 1$ and $p = 2$. Our first goal is to show

$$(39) \quad \|e^{(\tau+1)(L_\mu - \alpha\Lambda)} w_0\|_{\mathbb{X}(m)} \leq C e^{-\eta\tau} \|w_0\|_{\mathbb{X}(m)},$$

which in particular proves (20) with $\beta = 0$ and $p = 2$ for the vertical component of $e^{\tau(L_\mu - \alpha\Lambda)} w_0$. To this end we see that, due to the stretching effect in the vertical direction, the longtime dynamics of the semigroup $e^{\tau(L_\mu - \alpha\Lambda)}$ is dominated by the 2d vectorial problem analyzed in Proposition 3. The following result shows a simple but important stabilizing effect brought by the linear strain to realize this idea.

Lemma 5. *We have the following commutation property: for every $\mu > 1$ and $\alpha \in \mathbb{R}$,*

$$[\partial_3, L_\mu - \alpha\Lambda] = [\partial_3, \mathcal{L}_3] = -\frac{2\mu + 1}{2(\mu - 1)} \partial_3.$$

As a consequence, we have for all $\mu > 1$, $\alpha \in \mathbb{R}$, $k \in \mathbb{N}$, for all $\tau \in (0, \infty)$,

$$(40) \quad \partial_3^k e^{\tau(L_\mu - \alpha\Lambda)} = e^{-\frac{2\mu+1}{2(\mu-1)}k\tau} e^{\tau(L_\mu - \alpha\Lambda)} \partial_3^k.$$

This property of \mathcal{L}_3 is due to the stretching in the vertical direction and plays a crucial role in reducing the longtime dynamics to the 2d vectorial problem studied above. Indeed, since it is not difficult to show the naive bound $\|e^{\tau(L_\mu - \alpha\Lambda)}\|_{\mathbb{X}(m) \rightarrow \mathbb{X}(m)} \leq C_1 e^{C_0\tau}$ for all $\tau > 0$, where C_0 and C_1 may depend on α , μ , and m , (40) gives the bound

$$\begin{aligned} \|\partial_3^k e^{(\tau+1)(L_\mu - \alpha\Lambda)} w_0\|_{\mathbb{X}(m)} &\leq C_1 e^{C_0\tau - \frac{2\mu+1}{2(\mu-1)}k\tau} \|\partial_3^k e^{(L_\mu - \alpha\Lambda)} w_0\|_{\mathbb{X}(m)} \\ &\leq C_{1,k} e^{C_0\tau - \frac{2\mu+1}{2(\mu-1)}k\tau} \|w_0\|_{\mathbb{X}(m)}. \quad (\text{here (21) is used}) \end{aligned}$$

Hence, if k_0 is large enough depending on C_0 , we have

$$(41) \quad \|\partial_3^{k_0} e^{(\tau+1)(L_\mu - \alpha\Lambda)} w_0\|_{\mathbb{X}(m)} \leq C e^{-\frac{2\mu+1}{2(\mu-1)}\tau} \|w_0\|_{\mathbb{X}(m)}, \quad \tau > 0.$$

To obtain the decay estimate (39) for $e^{(\tau+1)(L_\mu - \alpha\Lambda)}$, rather than for $\partial_3^{k_0} e^{(\tau+1)(L_\mu - \alpha\Lambda)}$, we decompose the operator $L_\mu - \alpha\Lambda$ into two-dimensional part and three-dimensional part as follows:

$$(42) \quad (L_\mu - \alpha\Lambda)w = \mathcal{L}_{\mu,\alpha}w + \mathcal{L}_3w - \alpha \begin{pmatrix} 0 \\ 0 \\ \Lambda_3w - \tilde{\Lambda}_3w_3 \end{pmatrix} + \alpha\Lambda_4w,$$

where $\mathcal{L}_{\mu,\alpha}$ is defined in (30) and

$$\begin{aligned} \Lambda_3w - \tilde{\Lambda}_3w_3 &= ((K_{3d} * w)' - K_{2d} * w_3) \cdot \nabla' g, \\ \Lambda_4w &= g\partial_3(K_{3d} * w). \end{aligned}$$

The proof of the linear stability for the full three-dimensional problem relies on the decomposition (42) and on the following estimates for the three-dimensional part: for all $m \in (1, \infty]$ and $\sigma \in (0, 1)$, there exists $C(m, \sigma)$ such that

$$(43) \quad \begin{aligned} \|\Lambda_3w - \tilde{\Lambda}_3w_3\|_{X(m)} &\leq C(\|\partial_3w\|_{\mathbb{X}(m)} + \|w\|_{\mathbb{X}(m)}^\sigma \|\partial_3w\|_{\mathbb{X}(m)}^{1-\sigma}), \\ \|\Lambda_4w\|_{\mathbb{X}(m)} &\leq C\|\partial_3w\|_{\mathbb{X}(m)}. \end{aligned}$$

These estimates are exactly given in [7, Proposition 4.5], so we omit the proof of (43). The three-dimensional part is then treated as a perturbation of the 2d vectorial problem. The rest of the analysis leading to Proposition 2 is rigorously identical to [7, Section 4]; namely, it suffices to solve the integral equation

$$(44) \quad \begin{aligned} \tilde{w}(\tau) := e^{(\tau+1)(L_\mu - \alpha\Lambda)} w_0 &= e^{\tau(\mathcal{L}_{\mu,\alpha} + \mathcal{L}_3)} \left(e^{(L_\mu - \alpha\Lambda)} w_0 \right) \\ &\quad - \alpha \int_0^\tau e^{(\tau-s)(\mathcal{L}_{\mu,\alpha} + \mathcal{L}_3)} \left\{ \begin{pmatrix} 0 \\ 0 \\ \Lambda_3 \tilde{w} - \tilde{\Lambda}_3 \tilde{w}_3 \end{pmatrix} - \Lambda_4 \tilde{w} \right\} ds, \end{aligned}$$

with the a priori knowledge of the exponential decay of $\partial_3^{k_0} e^{(\tau+1)(L_\mu - \alpha\Lambda)}$ as in (41). Note that the semigroup $e^{\tau(\mathcal{L}_{\mu,\alpha} + \mathcal{L}_3)}$ is factorized as $e^{\tau\mathcal{L}_3} \otimes e^{\tau\mathcal{L}_{\mu,\alpha}}$, and hence, the estimate of $e^{\tau(\mathcal{L}_{\mu,\alpha} + \mathcal{L}_3)}$ is a consequence of (28) and Proposition 3. Then, by applying also (43) we have for (44),

$$(45) \quad \begin{aligned} &\|\tilde{w}(\tau)\|_{\mathbb{X}(m)} \\ &\leq C e^{-\eta\tau} \|\tilde{w}_0\|_{\mathbb{X}(m)} + C \int_0^\tau e^{-\eta(\tau-s)} (\|\partial_3 \tilde{w}\|_{\mathbb{X}(m)} + \|\tilde{w}\|_{\mathbb{X}(m)}^\sigma \|\partial_3 \tilde{w}\|_{\mathbb{X}(m)}^{1-\sigma})(s) ds. \end{aligned}$$

Here $\tilde{w}_0 = e^{(L_\mu - \alpha\Lambda)} w_0$ and C depends only on α , μ , m , and $\sigma \in (0, 1)$. Then the interpolation inequality $\|\partial_3 \tilde{w}\|_{\mathbb{X}(m)} \leq C \|\tilde{w}\|_{\mathbb{X}(m)}^{1-\frac{1}{k_0}} \|\partial_3^{k_0} \tilde{w}\|_{\mathbb{X}(m)}^{\frac{1}{k_0}}$ yields for any $\epsilon \in (0, 1)$,

$$\|\tilde{w}(\tau)\|_{\mathbb{X}(m)} \leq C e^{-\eta\tau} \|\tilde{w}_0\|_{\mathbb{X}(m)} + C \int_0^\tau e^{-\eta(\tau-s)} (\epsilon \|\tilde{w}\|_{\mathbb{X}(m)} + C_\epsilon \|\partial_3^{k_0} \tilde{w}\|_{\mathbb{X}(m)})(s) ds.$$

Note that the term $\int_0^\tau e^{-\eta(\tau-s)} \|\partial_3^{k_0} \tilde{w}(s)\|_{\mathbb{X}(m)} ds$ is bounded from above by $C e^{-\eta\tau} \|w_0\|_{\mathbb{X}(m)}$, in virtue of (41) and $\eta \in (0, \frac{1}{2}]$. Then, by taking ϵ small enough, one can show that $\|\tilde{w}(\tau)\|_{\mathbb{X}(m)} \leq C e^{-\frac{\eta}{2}\tau} \|\tilde{w}_0\|_{\mathbb{X}(m)} + C e^{-\eta\tau} \|w_0\|_{\mathbb{X}(m)}$. This estimate combined with the local (in time) estimate implies, in the end,

$$(46) \quad \|e^{\tau(L_\mu - \alpha\Lambda)} w_0\|_{\mathbb{X}(m)} \leq C e^{-\frac{\eta}{2}\tau} \|w_0\|_{\mathbb{X}(m)}, \quad \tau > 0.$$

The decay rate is then improved as follows. From (40) and (46) we have

$$(47) \quad \|\partial_3 e^{(\tau+1)(L_\mu - \alpha\Lambda)} w_0\|_{\mathbb{X}(m)} \leq C e^{-\frac{\eta}{2}\tau - \frac{2\mu+1}{2(\mu-1)}\tau} \|\partial_3 \tilde{w}_0\|_{\mathbb{X}(m)} \leq C e^{-\frac{\eta}{2}\tau - \frac{2\mu+1}{2(\mu-1)}\tau} \|w_0\|_{\mathbb{X}(m)}.$$

Then, (45) with σ close to 0 and (47) imply (39) and hence (20) for $\beta = 0$. For $\beta \neq 0$, (20) follows from (21), (39), and the identity

$$\partial_\xi^\beta e^{\tau(L_\mu - \alpha\Lambda)} w_0 = e^{-\frac{2\mu+1}{2(\mu-1)}\beta_3(\tau - \frac{1}{2})} \partial_{\xi'}^{\beta'} e^{\frac{1}{2}(L_\mu - \alpha\Lambda)} e^{(\tau-1)(L_\mu - \alpha\Lambda)} \partial_3^{\beta_3} e^{\frac{1}{2}(L_\mu - \alpha\Lambda)} w_0.$$

Next, to show (19), it suffices to consider the case $\beta = 0$. Fix a given number $\kappa \in (0, \eta + \frac{2\mu+1}{2(\mu-1)})$. As for the horizontal component of $e^{(\tau+1)(L_\mu - \alpha\Lambda)} w_0$, denoted by $\tilde{w}'(\tau)$, we have again from (44) and Proposition 3,

$$(48) \quad \|\tilde{w}'(\tau)\|_{X(m)^2} \leq C e^{-\kappa'\tau} \|\tilde{w}'_0\|_{X(m)^2} + C \int_0^\tau e^{-\kappa'(\tau-s)} \|\partial_3 \tilde{w}\|_{\mathbb{X}(m)}(s) ds.$$

Here $\kappa' \in (0, 1 + \frac{\mu+2}{2(\mu-1)})$ is taken so that $\kappa' > \kappa$, which is possible since $\eta \in (0, \frac{1}{2}]$ and $\kappa \in (0, \eta + \frac{2\mu+1}{2(\mu-1)})$. Note that (40) and (39) imply $\|\partial_3 e^{(\tau+1)(L_\mu - \alpha\Lambda)} w_0\|_{\mathbb{X}(m)} \leq C e^{-\eta\tau - \frac{2\mu+1}{2(\mu-1)}\tau} \|w_0\|_{\mathbb{X}(m)}$. Thus (48) gives the bound $\|\tilde{w}'(\tau)\|_{X(m)^2} \leq C e^{-\kappa\tau} \|w_0\|_{\mathbb{X}(m)}$,

as desired. In the case $\eta < \frac{1}{2}$ one can take the above κ' as $\kappa' > \eta + \frac{2\mu+1}{2(\mu-1)}$, which gives the decay rate $e^{-(\eta + \frac{2\mu+1}{2(\mu-1)})\tau}$ when $\eta < \frac{1}{2}$. This concludes the proof of Proposition 2.

2.4. Long time asymptotics for the full 3d linearized problem. In this subsection we show the asymptotic estimate of $e^{\tau(L_\mu - \alpha\Lambda)}$ for large τ . The main result is the estimate (57) below. Let $m > 2$ and let us introduce the projection \mathcal{P}_1 as

$$(49) \quad \mathcal{P}_1 f = \sum_{i=1,2} \theta_i[f_3] \partial_i G, \quad G = \begin{pmatrix} 0 \\ 0 \\ \frac{1}{4\pi} e^{-\frac{|\xi'|^2}{4}} \end{pmatrix}, \quad f \in \mathbb{X}(m).$$

Here $\theta_i[f_3](\xi_3) = -\int_{\mathbb{R}^2} \xi_i f_3(\xi', \xi_3) d\xi'$. Then \mathcal{P}_1 commutes with $e^{\tau\mathcal{L}_3}$ and we also note that \mathcal{P}_1 is motivated by the eigenprojection of $\mathcal{L}_{\mu,\alpha,3}$ for the eigenvalue $-\frac{1}{2}$. In particular, we have

$$(50) \quad (\mathcal{P}_1 e^{\tau(\mathcal{L}_{\mu,\alpha} + \mathcal{L}_3)} f)(\xi) = e^{-\frac{\tau}{2}} \sum_{i=1,2} (e^{\tau\mathcal{L}_3} \theta_i[f_3])(\xi_3) \partial_i G(\xi'), \quad f \in \mathbb{X}(m).$$

Set $w(\tau) = e^{\tau(L_\mu - \alpha\Lambda)} w_0$, $w_0 \in \mathbb{X}(m)$, which satisfies the statement in Proposition 2: since $m > 2$ we have

$$(51) \quad \|w(\tau)\|_{\mathbb{X}(m)} \leq C e^{-\frac{\tau}{2}} \|w_0\|_{\mathbb{X}(m)}, \quad \|\partial_3 w(\tau)\|_{\mathbb{X}(m)} \leq \frac{C e^{-(\frac{1}{2} + \frac{2\mu+1}{2(\mu-1)})\tau}}{a(\tau)^{\frac{1}{2}}} \|w_0\|_{\mathbb{X}(m)}.$$

As in (44), w satisfies the formula

$$(52) \quad w(\tau) = e^{\tau(\mathcal{L}_{\mu,\alpha} + \mathcal{L}_3)} w_0 - \alpha \int_0^\tau e^{(\tau-s)(\mathcal{L}_{\mu,\alpha} + \mathcal{L}_3)} \left(\begin{pmatrix} 0 \\ 0 \\ \Lambda_3 w - \tilde{\Lambda}_3 w_3 \end{pmatrix} - \Lambda_4 w \right) ds,$$

Let $\eta \in (\frac{1}{2}, 1]$ with $\eta < \frac{m-1}{2}$. Proposition 3 and (28) together with (43) yield

$$\begin{aligned} \|(I - \mathcal{P}_1)w(\tau)\|_{\mathbb{X}(m)} &\leq C e^{-\eta\tau} \|w_0\|_{\mathbb{X}(m)} \\ &\quad + C \int_0^\tau e^{-\eta(\tau-s)} (\|\partial_3 w\|_{\mathbb{X}(m)} + \|w\|_{\mathbb{X}(m)}^\sigma \|\partial_3 w\|_{\mathbb{X}(m)}^{1-\sigma})(s) ds. \end{aligned}$$

Since $\frac{2\mu+1}{2(\mu-1)} > 1$, we then have from (51) and by taking σ close to 0,

$$(53) \quad \begin{aligned} \|(I - \mathcal{P}_1)w(\tau)\|_{\mathbb{X}(m)} &\leq C e^{-\eta\tau} \|w_0\|_{\mathbb{X}(m)} + C \int_0^\tau e^{-\eta(\tau-s)} \frac{e^{-\frac{3}{2}s}}{a(s)^{\frac{1}{2}}} ds \|w_0\|_{\mathbb{X}(m)} \\ &\leq C e^{-\eta\tau} \|w_0\|_{\mathbb{X}(m)}. \end{aligned}$$

We also observe from (52) and the definition of \mathcal{P}_1 ,

$$(54) \quad \mathcal{P}_1 w(\tau) = e^{-\frac{\tau}{2}} \sum_{i=1,2} \left(e^{\tau\mathcal{L}_3} \theta_i[w_{0,3}] - \alpha \int_0^\tau e^{\frac{s}{2}} e^{(\tau-s)\mathcal{L}_3} h_i(s) ds \right) \partial_i G,$$

with

$$h_i(\xi_3, s) = - \int_{\mathbb{R}^2} \xi_i \left(\Lambda_3 w - \tilde{\Lambda}_3 w_3 - (\Lambda_4 w)_3 \right) (\xi', \xi_3, s) d\xi'.$$

Notice that h_i satisfies from (43) that

$$\begin{aligned} \|h_i(s)\|_{L^\infty(\mathbb{R})} &\leq C(\|\partial_3 w\|_{\mathbb{X}(m)} + \|w\|_{\mathbb{X}(m)}^\sigma \|\partial_3 w\|_{\mathbb{X}(m)}^{1-\sigma})(s) \\ &\leq \frac{C e^{-\frac{3}{2}s}}{a(s)^{\frac{1}{2}}} \|w_0\|_{\mathbb{X}(m)}, \quad (\text{from (51) and } \sigma \text{ is taken as close to } 0) \end{aligned}$$

which implies from (29), with $\chi = \frac{2\mu+1}{2(\mu-1)}$,

$$(55) \quad \lim_{\tau \rightarrow \infty} \left\| \int_0^\tau e^{\frac{s}{2}} e^{(\tau-s)\mathcal{L}_3} h_i(s) ds - \left(\frac{\chi}{2\pi}\right)^{\frac{1}{2}} \int_0^\infty e^{\frac{s}{2}} \int_{\mathbb{R}} e^{-\frac{\chi|\eta_3|^2}{2}} h_i(\eta_3, s) d\eta_3 ds \right\|_{L^\infty([-e^{(\chi-\delta)\tau}, e^{(\chi-\delta)\tau}])} = 0,$$

for any small $\delta > 0$. We also have again from (29) that

$$(56) \quad \lim_{\tau \rightarrow \infty} \left\| e^{\tau\mathcal{L}_3} \theta_i[w_{0,3}] - \left(\frac{\chi}{2\pi}\right)^{\frac{1}{2}} \int_{\mathbb{R}} e^{-\frac{\chi|\eta_3|^2}{2}} \theta_i[w_{0,3}](\eta_3) d\eta_3 \right\|_{L^\infty([-e^{(\chi-\delta)\tau}, e^{(\chi-\delta)\tau}])} = 0.$$

Thus, (53), (54), (55), and (56) give the following asymptotic estimate:

$$(57) \quad \lim_{\tau \rightarrow \infty} \left\| e^{\frac{\tau}{2}} e^{\tau(L_\mu - \alpha\Lambda)} w_0 - \left(\frac{\chi}{2\pi}\right)^{\frac{1}{2}} \sum_{i=1,2} \left(\int_{\mathbb{R}} e^{-\frac{\chi|\eta_3|^2}{2}} \theta_i[w_{0,3}] d\eta_3 - \alpha \int_0^\infty e^{\frac{s}{2}} \int_{\mathbb{R}} e^{-\frac{\chi|\eta_3|^2}{2}} h_i(\eta_3, s) d\eta_3 ds \right) \partial_i G \right\|_{L^\infty([-e^{(\chi-\delta)\tau}, e^{(\chi-\delta)\tau}]; L^2(m)^3)} = 0,$$

for any small $\delta > 0$. The similar convergence is valid also for $\nabla w'(\tau)$. Note that the coefficient in the expansion in (57) satisfy

$$\left(\frac{\chi}{2\pi}\right)^{\frac{1}{2}} \left| \int_{\mathbb{R}} e^{-\frac{\chi|\eta_3|^2}{2}} \theta_i[w_{0,3}] d\eta_3 - \alpha \int_0^\infty e^{\frac{s}{2}} \int_{\mathbb{R}} e^{-\frac{\chi|\eta_3|^2}{2}} h_i(\eta_3, s) d\eta_3 ds \right| \leq C \|w_0\|_{\mathbb{X}(m)},$$

with C depending only on α , m , and μ .

3. NONLINEAR STABILITY

This section is devoted to the analysis of the longtime behavior of the nonlinear system (13). We stress that the longtime behavior of solutions w to (13) immediately translates into information about the behavior of perturbations of the singular Burgers vortex near the blow-up time $T^* = 1$. Hence Theorem 1 is a direct consequence of the results of this section.

We prove that the solution 0 of

$$(58) \quad \partial_\tau \mathcal{W} - (L_\mu - \alpha\Lambda)\mathcal{W} = -\mathcal{V} \cdot \nabla \mathcal{W} + \mathcal{W} \cdot \nabla \mathcal{V} \quad \text{on } (0, \infty) \times \mathbb{R}^3$$

is asymptotically stable with respect to perturbations of the divergence-free initial data of the form

$$W_0 = W_{0,2d} + W_{0,3d}(\xi', \xi_3), \quad \text{with } W_{0,2d} = \begin{pmatrix} 0 \\ 0 \\ w_{0,2d}(\xi') \end{pmatrix}$$

where $w_{0,2d}$ is a scalar field in $L_0^2(m)$ of arbitrary size and $W_{0,3d}$ is small in $\mathbb{X}(m)$. The strategy we use is reminiscent of the paper [31]. We first study the stability of (58) with respect to arbitrarily large 2d perturbations $W_{0,2d}$ in $L_0^2(m)$. For this we rely on the result

of [10] about the longtime behavior of Navier-Stokes equations in \mathbb{R}^2 . Let us call (V_{2d}, W_{2d}) the solution to

$$(59) \quad \begin{aligned} \partial_\tau W_{2d} - (L_\mu - \alpha \mathbf{\Lambda})W_{2d} &= -V_{2d} \cdot \nabla W_{2d} + W_{2d} \cdot \nabla V_{2d} & \tau > 0, \xi \in \mathbb{R}^3, \\ W_{2d}|_{\tau=0} &= W_{0,2d}. \end{aligned}$$

This is in fact a two-dimensional problem and the solution is of the form $\begin{pmatrix} 0 \\ 0 \\ w_{2d}(\xi', \tau) \end{pmatrix}$,

and hence is reduced to the scalar equation for $w_{2d}(\xi', \tau)$ discussed in [10]. We will state the result for w_{2d} in Subsection 3.1 below. Then we study the stability of the solution 0 to the perturbed system around (V_{2d}, W_{2d}) with the small perturbation $W_{0,3d}$ in $\mathbb{X}(m)$ of the initial data. Precisely, we consider the solution $\mathcal{W} = w + W_{2d}$ to (58) with the initial data \mathcal{W}_0 , and thus, the equation for w reads

$$(60) \quad \begin{aligned} \partial_\tau w - (L_\mu - \alpha \mathbf{\Lambda})w \\ = -v \cdot \nabla w + w \cdot \nabla v - V_{2d} \cdot \nabla w - v \cdot \nabla W_{2d} + W_{2d} \cdot \nabla v + w \cdot \nabla V_{2d} =: F \end{aligned}$$

on $(0, \infty) \times \mathbb{R}^3$

where $v = K_{3D} * w$ is given by the Biot-Savart law. For this we use a fixed point argument treating the linear terms

$$-V_{2d} \cdot \nabla w - v \cdot \nabla W_{2d} + W_{2d} \cdot \nabla v + w \cdot \nabla V_{2d}$$

perturbatively.

Theorem 1 is a reformulation in the original variables of the following stability theorem.

Theorem 2 (nonlinear stability). *Let $\alpha \in \mathbb{R}$, $m \in (1, \infty]$ and $\mu \in (1, \infty)$. Let $w_{0,2d} \in L_0^2(m)$. For all $\eta \in (0, \frac{1}{2}]$ such that $\eta < \frac{m-1}{2}$, there exists $\varepsilon_0(\alpha, m, \mu, \eta, w_{0,2d}) \in (0, \infty)$, such that for all $W_{0,3d} \in \mathbb{X}(m)$, the condition*

$$\|W_{0,3d}\|_{\mathbb{X}(m)} \leq \varepsilon_0,$$

implies there exists a unique mild solution $\mathcal{W} \in L^\infty((0, \infty); \mathbb{X}(m)) \cap C^0([0, \infty); \mathbb{X}_{loc}(m))$

to (58) with the initial data $W_0 = \begin{pmatrix} 0 \\ 0 \\ w_{0,2d} \end{pmatrix} + W_{0,3d}$ satisfying

$$\|\partial_\xi^\beta (\mathcal{W}(\cdot, \tau) - W_{2d}(\cdot, \tau))\|_{\mathbb{X}(m)} \leq \frac{C}{a(\tau)^{\frac{|\beta|}{2}}} e^{-\eta\tau} \|W_{0,3d}\|_{\mathbb{X}(m)}, \quad \forall \tau \in (0, \infty).$$

Here $|\beta| \leq 1$ and C depends on α, m, μ, η , and $w_{0,2d}$. Moreover, if $m > 2$ then there exist $d_i \in \mathbb{R}$, $i = 1, 2$, such that

$$(61) \quad \lim_{\tau \rightarrow \infty} \sum_{|\beta| \leq 1} \left\| \partial_\xi^\beta (e^{\frac{\tau}{2}} \mathcal{W}(\cdot, \tau) - \sum_{i=1,2} (\lambda_i + d_i) \partial_i G(\cdot)) \right\|_{L_{\xi_3}^\infty([-e^{(\chi-\delta)\tau}, e^{(\chi-\delta)\tau}]; L^2(m)^3)} = 0,$$

for any $\delta > 0$. Here $\lambda_i = -\int_{\mathbb{R}^2} \xi_i w_{0,2d}(\xi') d\xi'$ and d_i satisfies $|d_i| \leq C \|W_{0,3d}\|_{\mathbb{X}(m)}$, and $\chi = \frac{2\mu+1}{2(\mu-1)} > 1$. If $W_{0,3d} = 0$ then $d_i = 0$ and (61) is valid in $L_{\xi_3}^\infty(\mathbb{R}; L^2(m)^3)$.

Remark 6. From the Biot-Savart law and (61) we have

$$(62) \quad \lim_{\tau \rightarrow \infty} \left\| e^{\frac{\tau}{2}} \mathcal{V}(\cdot, \tau) - \sum_{i=1,2} (\lambda_i + d_i) \partial_i U^G(\cdot) \right\|_{L_{\xi_3}^\infty([-e^{(\chi-\delta)\tau}, e^{(\chi-\delta)\tau}]; L_{\xi'}^\infty)} = 0,$$

for any $\delta > 0$. Since $\chi > 1$ we obtain (18) by rescaling back to the original variable.

3.1. Global stability with respect to 2d perturbations. We look for a solution W_{2d} of (59) in the form

$$W_{2d}(\xi', \tau) = \begin{pmatrix} 0 \\ 0 \\ w_{2d}(\xi', \tau) \end{pmatrix}.$$

We notice that

$$L_\mu W_{2d} = (\Delta' + \frac{1}{2}\xi' \cdot \nabla' + 1) \begin{pmatrix} 0 \\ 0 \\ w_{2d} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ L_{2d}w_{2d} \end{pmatrix}$$

and

$$\Lambda W_{2d} = (U^G)' \cdot \nabla' \begin{pmatrix} 0 \\ 0 \\ w_{2d} \end{pmatrix} + v' \cdot \nabla' \begin{pmatrix} 0 \\ 0 \\ g(\xi') \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \Lambda_{2d}w_{2d} \end{pmatrix}$$

so that (59) becomes the scalar equation

$$(63) \quad \begin{aligned} \partial_\tau w_{2d} - (L_{2d} - \alpha \Lambda_{2d})w_{2d} &= -v_{2d} \cdot \nabla w_{2d} & \tau > 0, \xi \in \mathbb{R}^3, \\ w_{2d}|_{\tau=0} &= w_{0,2d}. \end{aligned}$$

The stability of (63) was studied in full details. We recall here the result of [10]. Pay attention to the fact that the result in [10] is for the stability of the Oseen vortex with vorticity g , while we focus on the stability of the 0 solution of (63). In the end both viewpoints are of course equivalent since w solving (63) is nothing but the perturbation of the Oseen vortex.

Proposition 7 ([10, Proposition 1.5, 1.6 and Proposition 4.14]). *Let $m \in (1, \infty]$. For all divergence-free $w_{0,2d} \in L_0^2(m)$, there exists a unique global solution $w_{2d} \in C^0([0, \infty); L^2(m))$ and*

$$\|w_{2d}(\cdot, \tau)\|_{L^2(m)} \longrightarrow 0 \quad \text{when } \tau \rightarrow \infty.$$

Moreover, for all $\eta \in (0, \frac{1}{2}]$ such that $\eta < \frac{m-1}{2}$, for all $\beta \in \mathbb{N}^2$, $|\beta| \leq 1$, for all $w_{0,2d} \in L_0^2(m)$, there exists a constant $C(\eta, \beta, w_{0,2d}) < \infty$ such that

$$\|\partial_{\xi'}^\beta w_{2d}(\cdot, \tau)\|_{L^2(m)} \leq \frac{C e^{-\eta\tau}}{a(\tau)^{\frac{|\beta|}{2}}},$$

for all $\tau \in (0, \infty)$.

The result stated in [10] does not explicitly include the case $m = \infty$. However, the global stability for the case $m = \infty$ follows from the global stability for the case $m < \infty$. Indeed, the perturbed velocity $\|v_{2d}(\cdot, \tau)\|_\infty$ becomes small in long time in virtue of the result for $m < \infty$, which is enough to close the estimate of w_{2d} in $L^2(\infty)$. This argument is explicitly written in [6, Section 5.1]. Furthermore, let us remark that the fact that $w_{0,2d}$ is of integral zero over \mathbb{R}^2 , i.e. $w_{0,2d} \in L_0^2(m)$ is crucial. Otherwise, the perturbation w would not go to zero, since $\alpha g + w_{2d}$ would go to the Oseen vortex with total circulation $\alpha + \int_{\mathbb{R}^2} w_{0,2d}(\xi') d\xi'$. Notice that for $m > 2$, we have the decay

$$\|w_{2d}(\cdot, \tau)\|_{L^2(m)} \lesssim e^{-\frac{\tau}{2}},$$

which is sharp if one of the following moments is different from zero

$$\int_{\mathbb{R}^2} \xi_1 w_{0,2d}(\xi') d\xi' \neq 0 \quad \text{or} \quad \int_{\mathbb{R}^2} \xi_2 w_{0,2d}(\xi') d\xi' \neq 0.$$

The result of Gallay and Wayne goes even beyond the statement in Proposition 7, in the sense that the next term in the asymptotics of w_{2d} is given, see [10, display (80)] and Subsection 3.3 below.

3.2. Local stability with respect to 3d perturbations. Our next aim is to analyze the stability of (60) for general, but small in $\mathbb{X}(m)$, initial perturbations $W_{0,3d}$. The driving terms of the evolution are the linear terms $L_\mu - \alpha\mathbf{\Lambda}$. Hence, we treat the remaining terms as perturbations. Indeed the nonlinear terms

$$-v \cdot \nabla w + w \cdot \nabla v$$

are small because the initial data is small, and the linear terms

$$-V_{2d} \cdot \nabla w - v \cdot \nabla W_{2d} + W_{2d} \cdot \nabla v + w \cdot \nabla V_{2d}$$

are small in longtime thanks to the results of Proposition 7.

It follows from this observation that the solution w is a solution of the integral equation

$$\begin{aligned} w(\cdot, \tau) &= e^{\tau(L_\mu - \alpha\mathbf{\Lambda})} W_{0,3d} + \sum_{i=1}^2 \int_0^\tau e^{(\tau-\sigma)(L_\mu - \alpha\mathbf{\Lambda})} N_i(w, w) d\sigma \\ &\quad + \sum_{i=3}^6 \int_0^\tau e^{(\tau-\sigma)(L_\mu - \alpha\mathbf{\Lambda})} N_i(w) d\sigma \\ &= e^{\tau(L_\mu - \alpha\mathbf{\Lambda})} W_{0,3d} + \sum_{i=1}^2 \phi_i(w, w) + \sum_{i=3}^6 \phi_i(w) \\ &= \Phi(w)(\cdot, \tau), \end{aligned}$$

where

$$\begin{aligned} N_1(w, \tilde{w}) &= -(K_{3d} * w) \cdot \nabla \tilde{w}, & N_2(w, \tilde{w}) &= w \cdot \nabla (K_{3d} * \tilde{w}), \\ N_3(w) &= -V_{2d} \cdot \nabla w, & N_4(w) &= -(K_{3d} * w) \cdot \nabla W_{2d}, \\ N_5(w) &= W_{2d} \cdot \nabla (K_{3d} * w), & N_6(w) &= w \cdot \nabla V_{2d}, \end{aligned}$$

with K_{3d} the three-dimensional Biot-Savart kernel. Therefore, w is a fixed point of the map Φ .

Function space and a priori bounds. The linear evolution satisfies the estimates of Proposition 2. Let $m \in (1, \infty]$ and $\eta \in (0, \frac{1}{2}]$ such that $\eta < \frac{m-1}{2}$. We introduce the Banach space \mathbb{U} defined as follows

$$\begin{aligned} \mathbb{U} &= \left\{ w \in L^\infty((0, \infty); \mathbb{X}(m)) \cap C^0([0, \infty); \mathbb{X}_{loc}(m)); \nabla \cdot w(\cdot, \tau) = 0, \quad \forall \tau \in (0, \infty), \right. \\ &\quad \left. \|w\|_{\mathbb{U}} = \sum_{|\beta| \leq 1} \sup_{\tau > 0} a(\tau)^{\frac{|\beta|}{2}} e^{\eta\tau} \|\partial_\xi^\beta w(\cdot, \tau)\|_{\mathbb{X}(m)} < \infty \right\}. \end{aligned}$$

Notice that the definition of \mathbb{U} depends on η and m , though this dependence is not explicitly written. To deal with the linear perturbation terms ϕ_i for $i \in \{3, \dots, 6\}$ for the short time existence, we also introduce the space \mathbb{U}_T for given $T \in (0, \infty)$ defined as follows

$$\begin{aligned} \mathbb{U}_T &= \left\{ w \in L^\infty((0, T); \mathbb{X}(m)) \cap C^0([0, T]; \mathbb{X}_{loc}(m)); \nabla \cdot w(\cdot, \tau) = 0, \quad \forall \tau \in (0, T), \right. \\ &\quad \left. \|w\|_{\mathbb{U}_T} = \sum_{|\beta| \leq 1} \sup_{\tau \in (0, T)} a(\tau)^{\frac{|\beta|}{2}} e^{\eta\tau} \|\partial_\xi^\beta w(\cdot, \tau)\|_{\mathbb{X}(m)} < \infty \right\}. \end{aligned}$$

From Proposition 2, we now easily obtain the following estimate for the linear evolution

$$\|e^{\tau(L_\mu - \alpha\mathbf{\Lambda})} W_{0,3d}\|_{\mathbb{U}} \leq C_1 \|W_{0,3d}\|_{\mathbb{X}(m)},$$

with a constant $C_1(m, \eta, \mu) < \infty$.

The nonlinear terms ϕ_1 and ϕ_2 can be handled exactly as in [7, Section 5] using [7, Corollary 2.4]. For all $p \in (1, 2)$, there exists a constant $C(m, p) < \infty$ such that for all $w, \tilde{w} \in \mathbb{X}(m)$, for all $i \in \{1, 2\}$,

$$\|N_i(w, \tilde{w})\|_{X^p(m)^3} \leq C \|w\|_{\mathbb{X}(m)} \|\nabla \tilde{w}\|_{\mathbb{X}(m)}.$$

Hence following the estimates in [7, p. 503], for all $p \in (1, 2)$, there exists a constant $C(m, p, \eta) < \infty$, for all $\beta \in \mathbb{N}^3$, $|\beta| \leq 1$, for all $i \in \{1, 2\}$, for all $w, \tilde{w} \in \mathbb{X}(m)$,

$$(64) \quad \left\| \partial_x^\beta \phi_i(w, \tilde{w}) \right\|_{\mathbb{X}(m)} \leq \frac{C e^{-\eta\tau}}{a(\tau)^{\frac{1}{p} + \frac{|\beta|}{2} - 1}} \|w\|_{\mathbb{U}} \|\tilde{w}\|_{\mathbb{U}} \leq \frac{C e^{-\eta\tau}}{a(\tau)^{\frac{|\beta|}{2}}} \|w\|_{\mathbb{U}} \|\tilde{w}\|_{\mathbb{U}},$$

using that $p > 1$ and that a is bounded for the last inequality. Moreover, for $w \in \mathbb{U}$, we have $\nabla \cdot w = 0$ by definition, which implies

$$\int_{\mathbb{R}^2} (N_1(w, w) + N_2(w, w))_3 d\xi' = \int_{\mathbb{R}^2} \nabla' \cdot (w' v_3 - v' w_3) d\xi' = 0.$$

Therefore, $N_1(w, w) + N_2(w, w) \in \mathbb{X}^p(m)$ and hence

$$\int_{\mathbb{R}^2} (\phi_1(w, w) + \phi_2(w, w))_3 d\xi' = 0.$$

By estimate (64), $\phi_1(w, w) + \phi_2(w, w)$ in addition belongs to \mathbb{U} and

$$\|\phi_1(w, w) + \phi_2(w, w)\|_{\mathbb{U}} \leq C_2 \|w\|_{\mathbb{U}}^2,$$

with a constant $C_2(m, p, \eta) < \infty$.

We now turn to the linear terms $\phi_i(w)$, for $i \in \{3, \dots, 6\}$. These terms are negligible in longtime due to the exponential decay exhibited in Proposition 7. In short time however, there is no obvious decay. We will use the factor $a(\tau)^{-\frac{1}{p}+1}$ neglected in the estimate (64) of the nonlinear terms in order to gain smallness. Thanks to Proposition 7, we can estimate directly: for all $p \in (1, 2)$, there exists a constant $C(m, p, \eta, W_{0,2d}) < \infty$ such that for all $w \in \mathbb{X}(m)$, for $i \in \{3, 5\}$,

$$\|N_i(w)\|_{X^p(m)^3} \leq C \|w_{2d}\|_{L^2(m)} \|\nabla w\|_{\mathbb{X}(m)} \leq C e^{-\eta\tau} \|\nabla w\|_{\mathbb{X}(m)} \leq \frac{C e^{-2\eta\tau}}{a(\tau)^{\frac{1}{2}}} \|w\|_{\mathbb{U}},$$

and for $i \in \{4, 6\}$,

$$\|N_i(w)\|_{X^p(m)^3} \leq C \|\nabla w_{2d}\|_{L^2(m)} \|w\|_{\mathbb{X}(m)} \leq \frac{C e^{-\eta\tau}}{a(\tau)^{\frac{1}{2}}} \|w\|_{\mathbb{X}(m)} \leq \frac{C e^{-2\eta\tau}}{a(\tau)^{\frac{1}{2}}} \|w\|_{\mathbb{U}}.$$

Therefore, one can estimate ϕ_i , for $i \in \{3, \dots, 6\}$ in the exact same way as the nonlinear terms ϕ_i for $i \in \{1, 2\}$ above. This yields for all $p \in (1, 2)$, there exists a constant $C(m, p, \eta, W_{0,2d}) < \infty$, for all $\beta \in \mathbb{N}^3$, $|\beta| \leq 1$, for all $i \in \{3, \dots, 6\}$, for all $w \in \mathbb{X}(m)$,

$$(65) \quad \left\| \partial_x^\beta \phi_i(w) \right\|_{\mathbb{X}(m)} \leq \frac{C e^{-\eta\tau}}{a(\tau)^{\frac{1}{p} + \frac{|\beta|}{2} - 1}} \|w\|_{\mathbb{U}},$$

Contrary to the nonlinear terms, here we keep the factor $a(\tau)^{-\frac{1}{p}+1}$ which is used to give smallness in short time, using the immediate inequality

$$(66) \quad a(\tau) \leq \tau, \quad \forall \tau \in (0, \infty).$$

It remains to see that the horizontal moments of the third components of $N_3(w) + N_6(w)$ on the one hand and $N_4(w) + N_5(w)$ on the other hand are zero. Indeed,

$$\begin{aligned} \int_{\mathbb{R}^2} (N_3(w) + N_6(w))_3 d\xi' &= \int_{\mathbb{R}^2} -V'_{2d} \cdot \nabla' w_3 + w' \cdot \nabla' V'_{2d,3} d\xi' \\ &= - \int_{\mathbb{R}^2} \nabla' \cdot (V'_{2d} w_3) d\xi' = 0 \end{aligned}$$

and

$$\begin{aligned} \int_{\mathbb{R}^2} (N_4(w) + N_5(w))_3 d\xi' &= \int_{\mathbb{R}^2} -v' \cdot \nabla' W_{2d,3} + W_{2d,3} \partial_3 v_3 d\xi' \\ &= - \int_{\mathbb{R}^2} \nabla \cdot (v' W_{2d,3}) d\xi' = 0. \end{aligned}$$

Thus, $\phi_3(w) + \dots + \phi_6(w)$ belongs to \mathbb{U} and we have the estimate

$$\left\| \sum_{i=3}^6 \phi_i(w) \right\|_{\mathbb{U}} \leq C_3 \|w\|_{\mathbb{U}}$$

as well as

$$\left\| \sum_{i=3}^6 \phi_i(w) \right\|_{\mathbb{U}_T} \leq C_3 T^{1-\frac{1}{p}} \|w\|_{\mathbb{U}_T}$$

using (66), for all $T \in (0, \infty)$, with a constant $C_3(m, p, \eta, W_{0,2d}) < \infty$.

Short time existence on $(0, T)$. Let $p \in (1, 2)$. To put it in a nutshell, for $T \in (0, \infty)$, we proved for all $w \in \mathbb{U}$

$$\|\Phi(w)\|_{\mathbb{U}} \leq C_1 \|W_{0,3d}\|_{\mathbb{X}(m)} + C_2 \|w\|_{\mathbb{U}}^2 + C_3 \|w\|_{\mathbb{U}},$$

$$\|\Phi(w)\|_{\mathbb{U}_T} \leq C_1 \|W_{0,3d}\|_{\mathbb{X}(m)} + C_2 \|w\|_{\mathbb{U}_T}^2 + C_3 T^{1-\frac{1}{p}} \|w\|_{\mathbb{U}_T}$$

and for all $w, \tilde{w} \in \mathbb{U}_T$

$$\|\Phi(w) - \Phi(\tilde{w})\|_{\mathbb{U}_T} \leq C_2 (\|w\|_{\mathbb{U}_T} + \|\tilde{w}\|_{\mathbb{U}_T}) \|w - \tilde{w}\|_{\mathbb{U}_T} + C_3 T^{1-\frac{1}{p}} \|w - \tilde{w}\|_{\mathbb{U}_T}$$

The goal is now to choose $T \in (0, \infty)$, $\delta > 0$ and $K > 0$ such that if $W_{0,3d} \in B_{\mathbb{X}(m)}(0, \delta)$, then Φ maps $B_{\mathbb{U}_T}(0, K)$ into itself and is a contraction on this ball. In order to realize this, it is enough to take T, δ and K such that

$$C_3 T^{1-\frac{1}{p}} < \frac{1}{2}, \quad 2C_2 K < \frac{1}{2} \quad \text{and} \quad \delta < \frac{K}{4C_1}.$$

Therefore, there exists a unique fixed point w for Φ in \mathbb{U}_T .

Longtime existence and decay. It remains to extend the solution on $(0, \infty)$ and to prove decay estimates for w . Let T be fixed for the whole discussion as above

$$C_3 T^{1-\frac{1}{p}} < \frac{1}{2}.$$

We use the fact that W_{2d} and V_{2d} decay fast in time. One of the arguments we use repeatedly is the following. For $j \in \mathbb{N}$, $j \geq 1$, we consider w_j defined by $w_j(\cdot, \tau) = w(\cdot, \tau + jT)$ for all $\tau \in (0, \infty)$ and which solves

$$(67) \quad \begin{aligned} \partial_\tau w_j - (L_\mu - \alpha \mathbf{\Lambda}) w_j &= -v_j \cdot \nabla w_j + w_j \cdot \nabla v_j \\ -V_{2d}^{(j)} \cdot \nabla w_j - v_j \cdot \nabla W_{2d}^{(j)} + W_{2d}^{(j)} \cdot \nabla v_j + w_j \cdot \nabla V_{2d}^{(j)}, & \quad \tau > 0, \xi \in \mathbb{R}^3, \\ w_j|_{\tau=0} &= w(\cdot, jT), \end{aligned}$$

where $v_j = K_{3d} * w_j$, $V_{2d}^{(j)} = V_{2d}(jT + \cdot)$ and $W_{2d}^{(j)} = W_{2d}(jT + \cdot)$. We rewrite this system as an integral equation, defining the shifted version of the mapping Φ , $\Phi^{(j)}$, in an obvious way. Notice that the smallness of $V_{2d}^{(j)}$ and $W_{2d}^{(j)}$ follows easily from the exponential decay of V_{2d} and W_{2d} . Hence we obtain, following the same estimates as above for Φ but with V_{2d} and W_{2d} replaced by $V_{2d}^{(j)}$ and $W_{2d}^{(j)}$, for all $w \in \mathbb{U}$

$$\|\Phi^{(j)}(w)\|_{\mathbb{U}} \leq C_1 \|w(\cdot, jT)\|_{\mathbb{X}(m)} + C_2 \|w\|_{\mathbb{U}}^2 + C_3 e^{-\eta jT} \|w\|_{\mathbb{U}}$$

and for all $w, \tilde{w} \in \mathbb{U}$

$$\|\Phi^{(j)}(w) - \Phi^{(j)}(\tilde{w})\|_{\mathbb{U}} \leq C_2 (\|w\|_{\mathbb{U}} + \|\tilde{w}\|_{\mathbb{U}}) \|w - \tilde{w}\|_{\mathbb{U}} + C_3 e^{-\eta jT} \|w - \tilde{w}\|_{\mathbb{U}}.$$

For all $w, \tilde{w} \in \mathbb{U}_T$,

(68)

$$\begin{aligned} \|\Phi^{(j)}(w)\|_{\mathbb{U}_T} &\leq C_1 \|w(\cdot, jT)\|_{\mathbb{X}(m)} + C_2 \|w\|_{\mathbb{U}_T}^2 + C_3 e^{-\eta jT} T^{1-\frac{1}{p}} \|w\|_{\mathbb{U}_T}, \\ \|\Phi^{(j)}(w) - \Phi^{(j)}(\tilde{w})\|_{\mathbb{U}_T} &\leq C_2 (\|w\|_{\mathbb{U}_T} + \|\tilde{w}\|_{\mathbb{U}_T}) \|w - \tilde{w}\|_{\mathbb{U}_T} + C_3 e^{-\eta jT} T^{1-\frac{1}{p}} \|w - \tilde{w}\|_{\mathbb{U}_T} \\ &\leq C_2 (\|w\|_{\mathbb{U}_T} + \|\tilde{w}\|_{\mathbb{U}_T}) \|w - \tilde{w}\|_{\mathbb{U}_T} + C_3 T^{1-\frac{1}{p}} \|w - \tilde{w}\|_{\mathbb{U}_T} \end{aligned}$$

The idea is to iterate the short time construction as long as $C_3 e^{-\eta jT} \geq \frac{1}{2}$. Let k be the least integer such as

$$(69) \quad C_3 e^{-\eta kT} < \frac{1}{2}.$$

Notice that $k(m, \eta, p) < \infty$. Let K_∞ be such that

$$(70) \quad 2C_2 K_\infty < \frac{1}{2}.$$

We subsequently iterate k times the short time construction in order to have a solution in $(0, kT)$. Then, we can construct the solution directly in (kT, ∞) based on the fact that the perturbative terms are small uniformly in that time interval. For all $j \in \{0, k+1\}$, let

$$K_j = \frac{1}{4C_1} K_{j+1} \quad \text{so that} \quad K_j = \left(\frac{1}{4C_1}\right)^{k+2-j} K_\infty.$$

Let us explain the induction. First for $k=0$, we construct the solution in $(0, T)$. This was above, in the local in time construction of a solution. We take $\delta = K_0$ and $K = K_1$. By our choice of parameters and estimates (68), we obtain the existence of a unique solution to (60), which satisfies

$$\|w\|_{\mathbb{U}_T} \leq K_1 \quad \text{and moreover, by definition of } \mathbb{U}_T, \quad \|w(\cdot, \tau)\|_{\mathbb{X}(m)} \leq K_1 e^{-\eta\tau}, \quad \forall \tau \in (0, T).$$

We can now iterate the construction. Let $j \in \{1, k-1\}$. Assume that we have a solution w on $(0, jT)$ such that

$$(71) \quad w \in L^\infty((0, jT); \mathbb{X}(m)) \cap C^0([0, jT]; \mathbb{X}_{loc}(m)); \quad \nabla \cdot w(\cdot, \tau) = 0 \quad \forall \tau \in (0, T)$$

and

$$(72) \quad \|w(\cdot, \tau)\|_{\mathbb{X}(m)} \leq K_j e^{-\eta\tau}, \quad \forall \tau \in (0, T).$$

Then, we aim at extending the solution on $(0, (j+1)T)$. In order to do so, we consider the shifted solution w_j to (67). By (68) we have

$$\begin{aligned} \|\Phi^{(j)}(w)\|_{\mathbb{U}_T} &\leq C_1 K_j e^{-\eta j T} + C_2 K_{j+1} \|w\|_{\mathbb{U}_T} + C_3 e^{-\eta j T} T^{1-\frac{1}{p}} K_{j+1}, \\ &\leq \frac{3e^{-\eta j T}}{4} K_{j+1} + \frac{1}{4} \|w\|_{\mathbb{U}_T} \\ &\leq K_{j+1} \\ \|\Phi^{(j)}(w) - \Phi^{(j)}(\tilde{w})\|_{\mathbb{U}_T} &\leq (2C_2 K_{j+1} + C_3 T^{1-\frac{1}{p}}) \|w - \tilde{w}\|_{\mathbb{U}_T} \\ &\leq A \|w - \tilde{w}\|_{\mathbb{U}_T}, \end{aligned}$$

with $A < 1$. Therefore, there exists a unique fixed point w_j such that

$$\|w_j\|_{\mathbb{U}_T} \leq K_{j+1}.$$

Furthermore, thanks to the bound

$$\|w_j\|_{\mathbb{U}_T} = \|\Phi^{(j)}(w)\|_{\mathbb{U}_T} \leq \frac{3e^{-\eta j T}}{4} K_{j+1} + \frac{1}{4} \|w\|_{\mathbb{U}_T}$$

we obtain

$$\|w_j\|_{\mathbb{U}_T} \leq K_{j+1} e^{-\eta j T},$$

which implies

$$\|w(\cdot, \tau)\|_{\mathbb{X}(m)} \leq K_{j+1} e^{-\eta \tau}, \quad \forall \tau \in (0, (j+1)T),$$

where w is the concatenation of w defined on $(0, jT)$ and $w_j(\cdot, \cdot - jT)$ on $(jT, (j+1)T)$. Hence, we have the recurrence hypothesis (71) and (72) at rank $j+1$.

It remains to construct a solution on (kT, ∞) . This can now be done in one step since we do not need the smallness of the parameter T any longer to make $C_3 e^{-\eta k T} K_\infty$ small. By the condition (69), we have

$$C_3 e^{-\eta k T} K_\infty < \frac{1}{2} K_\infty.$$

Therefore, we can easily show that there exists a unique w_{k+1} on $(0, \infty)$ such that

$$\|w_{k+1}\|_{\mathbb{U}} \leq K_\infty.$$

Concatenating this solution with the one on $(0, kT)$ and using the previous estimates, we arrive at the existence of w such that

$$w \in L^\infty((0, \infty); \mathbb{X}(m)) \cap C^0([0, \infty); \mathbb{X}_{loc}(m)), \quad \nabla \cdot w(\cdot, \tau) = 0, \quad \forall \tau \in (0, \infty)$$

and

$$\|w(\cdot, \tau)\|_{\mathbb{X}(m)} \leq K_\infty e^{-\eta \tau}, \quad \forall \tau \in (0, \infty).$$

This ends the proof of Theorem 2.

Remark 8. Notice that the size of 3d perturbations $\|W_{0,3d}\|_{\mathbb{X}(m)}$ that are allowed in the argument above depends on $w_{0,2d}$ through the constant C_3 . Indeed,

$$\|W_{0,3d}\|_{\mathbb{X}(m)} \leq \delta \simeq \frac{1}{4C_2} e^{-(k+2) \log(4C_1)}.$$

From our choice of parameters, we have the following rough estimates: $T \simeq (2C_3)^{-\frac{1}{1-\frac{1}{p}}}$, hence from (69)

$$k \simeq \frac{1}{\eta T} \log(2C_3) \simeq \frac{1}{\eta} (2C_3)^{\frac{1}{1-\frac{1}{p}}} \log(2C_3).$$

3.3. Secondary blow-up profile. Let $\alpha \in \mathbb{R}$, $\alpha \neq 0$ be fixed. Let $\nu \in (\frac{1}{2}, 1]$ and $m > 2\nu + 1$. Note that we have constructed the solution to (58) of the form

$$\mathcal{W}(\xi, \tau) = \begin{pmatrix} 0 \\ 0 \\ w_{2d}(\xi', \tau) \end{pmatrix} + w(\xi, \tau),$$

with

$$(73) \quad \begin{aligned} \sup_{\tau \geq 0} \sum_{|\beta| \leq 1} e^{\frac{\tau}{2}} a(\tau)^{\frac{|\beta|}{2}} \|\partial_\xi^\beta w_{2d}(\tau)\|_{L^2(m)} &\leq C(W_{0,2d}), \\ \sup_{\tau \geq 0} \sum_{|\beta| \leq 1} e^{\frac{\tau}{2}} a(\tau)^{\frac{|\beta|}{2}} \|\partial_\xi^\beta w(\tau)\|_{\mathbb{X}(m)} &\leq C\|W_{0,3d}\|_{\mathbb{X}(m)} \ll 1. \end{aligned}$$

Notice in addition that by Gally-Wayne [10, Eq.(80)] with the smoothing effect of the system we have

$$(74) \quad \begin{aligned} \sup_{\tau \geq 0} \sum_{|\beta| \leq 1} e^{\nu\tau} a(\tau)^{\frac{|\beta|}{2}} \left\| \partial_\xi^\beta \left(w_{2d}(\tau) - e^{-\frac{\tau}{2}} \sum_{i=1,2} \lambda_i \partial_i g \right) \right\|_{L^2(m)} &\leq C(W_{0,2d}), \\ \lambda_i &= - \int_{\mathbb{R}^2} \xi_i w_{0,2d}(\xi') d\xi'. \end{aligned}$$

Then (73) and (74) yield from the Biot-Savart law,

$$(75) \quad \limsup_{\tau \rightarrow \infty} \left\| e^{\frac{\tau}{2}} \mathcal{V}(\tau) - \sum_{i=1,2} \lambda_i \partial_i U^G \right\|_{L^\infty} \leq C\|W_{0,3d}\|_{\mathbb{X}(m)}.$$

Theorem 1 now follows from rescaling Theorem 2 and the above estimate (75) for the velocity.

It remains to show the last statement of Theorem 2. We observe from (60) that w is the solution to

$$(76) \quad w(\tau) = e^{\tau(L_\mu - \alpha\Lambda)} W_{0,3d} + \int_0^\tau e^{(\tau-s)(L_\mu - \alpha\Lambda)} F(s) ds,$$

where we already know that $F(s)$ satisfies the estimate

$$(77) \quad \|F(s)\|_{\mathbb{X}(m)} \leq \frac{C}{a(s)^{\frac{3}{4}}} e^{-\frac{3}{4}s} \|W_{0,3d}\|_{\mathbb{X}(m)}, \quad C = C(W_{0,2d}).$$

Then (57) implies that for each $f \in \mathbb{X}(m)$ with $m > 2$ there exist $c_i[f] \in \mathbb{R}$, $i = 1, 2$, such that

$$(78) \quad \lim_{\tau \rightarrow \infty} \sum_{|\beta| \leq 1} \left\| \partial_\xi^\beta \left(e^{\frac{\tau}{2}} e^{\tau(L_\mu - \alpha\Lambda)} f - \sum_{i=1,2} c_i[f] \partial_i G \right) \right\|_{L_{\xi_3}^\infty([-e^{(\chi-\delta)\tau}, e^{(\chi-\delta)\tau}]; L^2(m)^3)} = 0,$$

for any $\delta > 0$. Here $\chi = \frac{2\mu+1}{2(\mu-1)} > 1$ and the coefficients $c_i[f]$ satisfy

$$|c_i[f]| \leq C\|f\|_{\mathbb{X}(m)}.$$

Thus, by combining (77), (78), and the estimate $\|\partial_\xi^\beta e^{\tau(L_\mu - \alpha\Lambda)} f\|_{\mathbb{X}(m)} \leq C a(\tau)^{-\frac{|\beta|}{2}} e^{-\frac{\tau}{2}} \|f\|_{\mathbb{X}(m)}$, we have from the integral equation (76) that

$$(79) \quad \begin{aligned} \lim_{\tau \rightarrow \infty} \sum_{|\beta| \leq 1} \left\| \partial_\xi^\beta \left(e^{\frac{\tau}{2}} w(\tau) \right. \right. \\ \left. \left. - \sum_{i=1,2} \left(c_i[W_{0,3d}] + \int_0^\infty e^{\frac{s}{2}} c_i[F(s)] ds \right) \partial_i G \right) \right\|_{L_{\xi_3}^\infty([-e^{(\chi-\delta)\tau}, e^{(\chi-\delta)\tau}]; L^2(m)^3)} = 0. \end{aligned}$$

Hence, collecting (74) and (79), we obtain

$$(80) \quad \lim_{\tau \rightarrow \infty} \sum_{|\beta| \leq 1} \left\| \partial_{\xi}^{\beta} \left(e^{\frac{\tau}{2}} \mathcal{W}(\tau) - \sum_{i=1,2} (\lambda_i + d_i) \partial_i G \right) \right\|_{L_{\xi_3}^{\infty}([-e^{(\chi-\delta)\tau}, e^{(\chi-\delta)\tau}]; L^2(m)^3)} = 0$$

for any $\delta > 0$, where the coefficients $d_i \in \mathbb{R}$ satisfies $|d_i| \leq C \|W_{0,3d}\|_{\mathbb{X}(m)} \ll 1$ with $C = C(\alpha, m, \mu, W_{0,2d})$. In particular, the last statement of Theorem 2 holds. The proof is complete.

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